

Can we calculate things better?

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What does our solver look like now?

$$\begin{array}{l} \mathbf{x}(t + \Delta t) = \mathbf{x}(t) + \dot{\mathbf{x}} \Delta t \\ \dot{\mathbf{x}}(t + \Delta t) = \dot{\mathbf{x}}(t) + \mathbf{a}(t) \Delta t \end{array} + O(\Delta t^2)$$

We say “first order solver”
since errors are on order of
 Δt^2

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Hermite Solver

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$$\begin{aligned} \mathbf{x}_1 &= \mathbf{x}_0 + \frac{1}{2}(\dot{\mathbf{x}}_1 + \dot{\mathbf{x}}_0)\Delta t + \frac{1}{12}(\mathbf{a}_0 - \mathbf{a}_1)\Delta t^2 + \mathcal{O}(\Delta t^5) \\ \dot{\mathbf{x}}_1 &= \dot{\mathbf{x}}_0 + \frac{1}{2}(\mathbf{a}_1 + \mathbf{a}_0)\Delta t + \frac{1}{12}(\dot{\mathbf{a}}_0 - \dot{\mathbf{a}}_1)\Delta t^2 + \mathcal{O}(\Delta t^5) \end{aligned}$$

4th order solver

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4th order solver

$$\begin{aligned} \mathbf{x}_p &= \mathbf{x}_0 + \dot{\mathbf{x}}_0 \Delta t + \frac{1}{2} \mathbf{a}_0 \Delta t^2 + \frac{1}{6} \dot{\mathbf{a}}_0 \Delta t^3 \\ \dot{\mathbf{x}}_p &= \dot{\mathbf{x}}_0 + \mathbf{a}_0 \Delta t + \frac{1}{2} \dot{\mathbf{a}}_0 \Delta t^2 \end{aligned}$$

Need “predictive” step for \mathbf{a} and “jerk” $\dot{\mathbf{a}}$ otherwise this is circular (need \mathbf{x}_1 for \mathbf{a}_1 , but need \mathbf{a}_1 for \mathbf{x}_1 ...)

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See Resources section for more information about integrators.

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One more thing: “Gravitational Units”

Basically: $G = M = R = 1$

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N-body Units

A conventional system of units in which

$$G = 1$$

$$M = 1$$

$$R = 1$$

Example

Suppose a star cluster has $M = 10^5 M_\odot$, $R = 5 \text{ pc}$. To convert a velocity from the *N*-body code to km/s, multiply by $\sqrt{\frac{GM}{R}}$, where G is expressed in the same units (i.e. km/s, M_\odot , pc), i.e. $G \simeq 0.043$.

On day 3 website:

Some code that compares Hermite and Euler Integration Schemes with Analytical

www.astroblend.com/ba2017/code/day3/twobodyintegrators_eu_and_hermite_jills.py