

A Week of Computational Astronomy

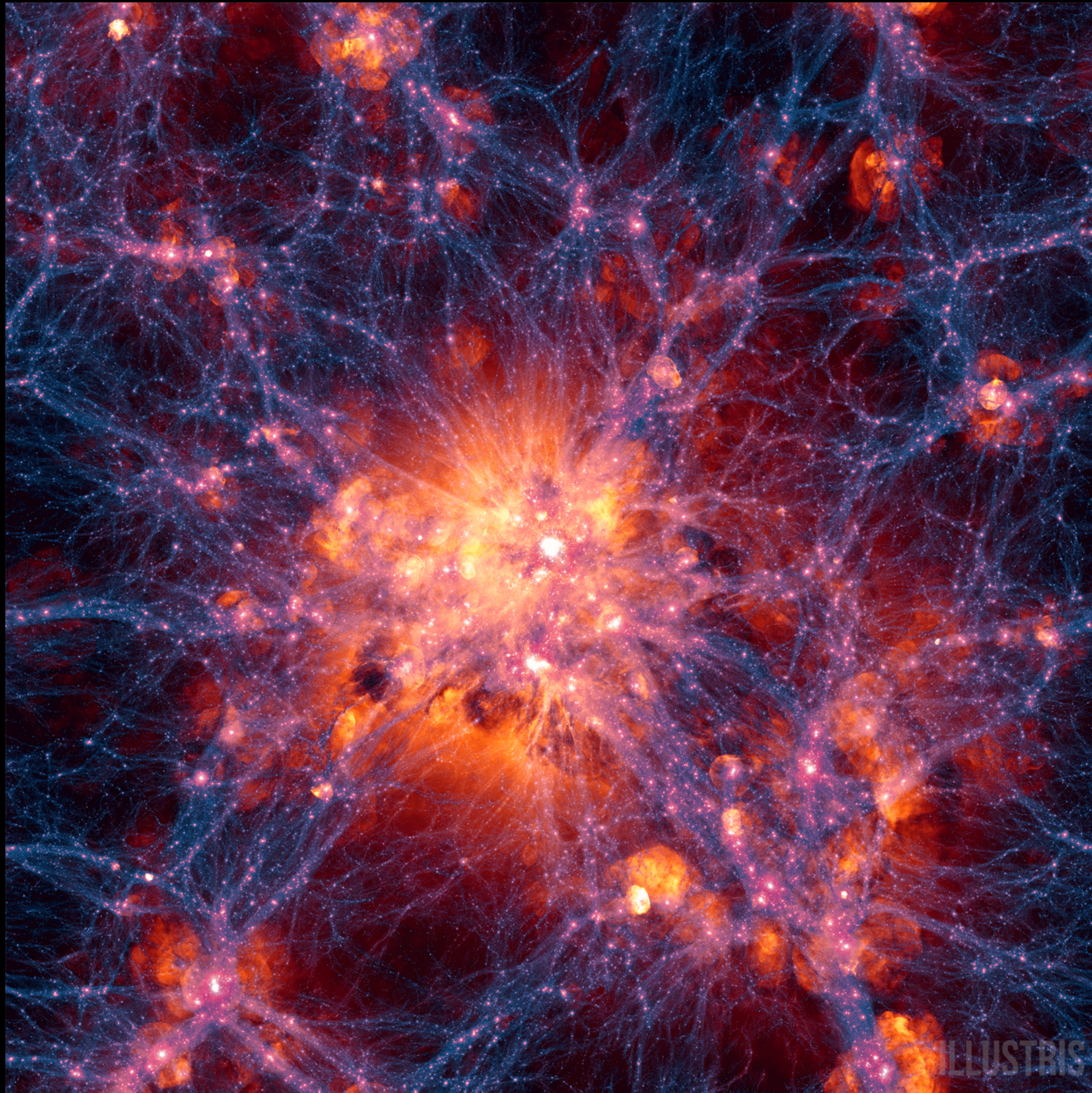
www.astroblend.com/ba2016

A Week of Computational Astronomy

... beginning with some motivation
(aka super cool movies and pictures)

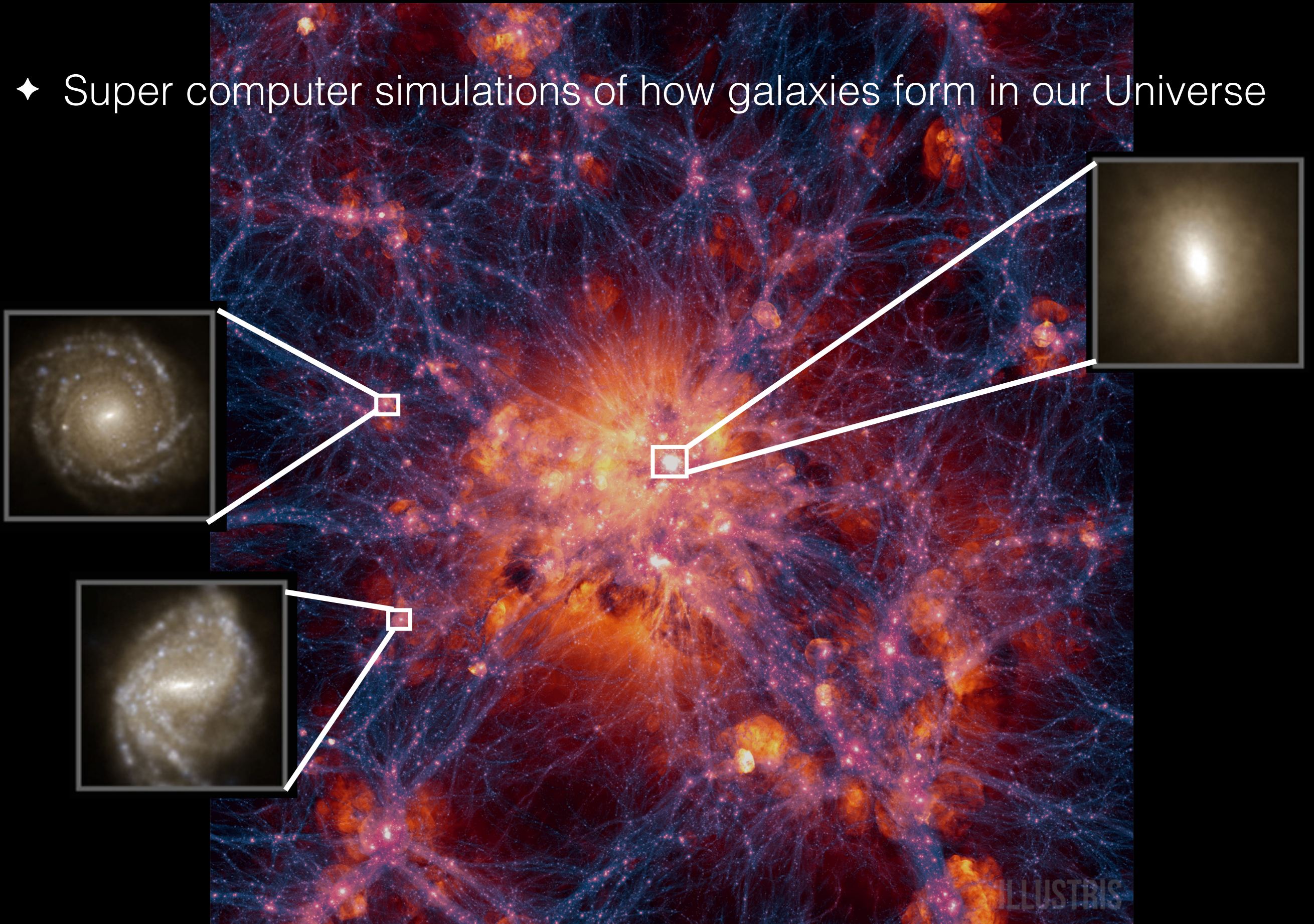
- (1) Who am I?
- (2) What are we doing?
- (3) How are we gonna do it?

Who are you and what do you do?



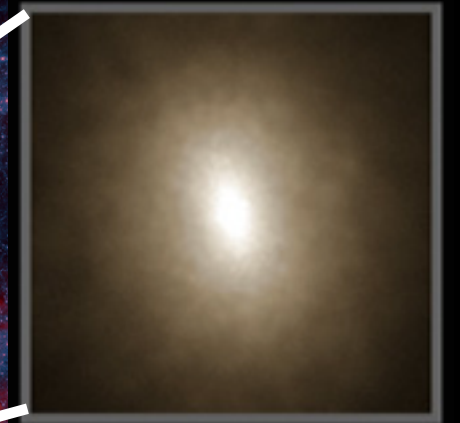
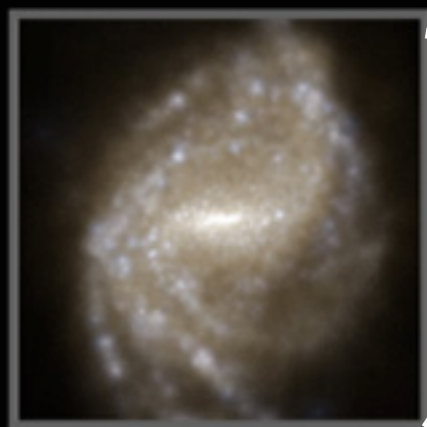
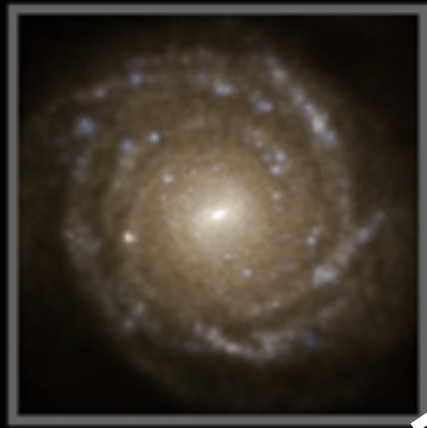
Who are you and what do you do?

- ◆ Super computer simulations of how galaxies form in our Universe



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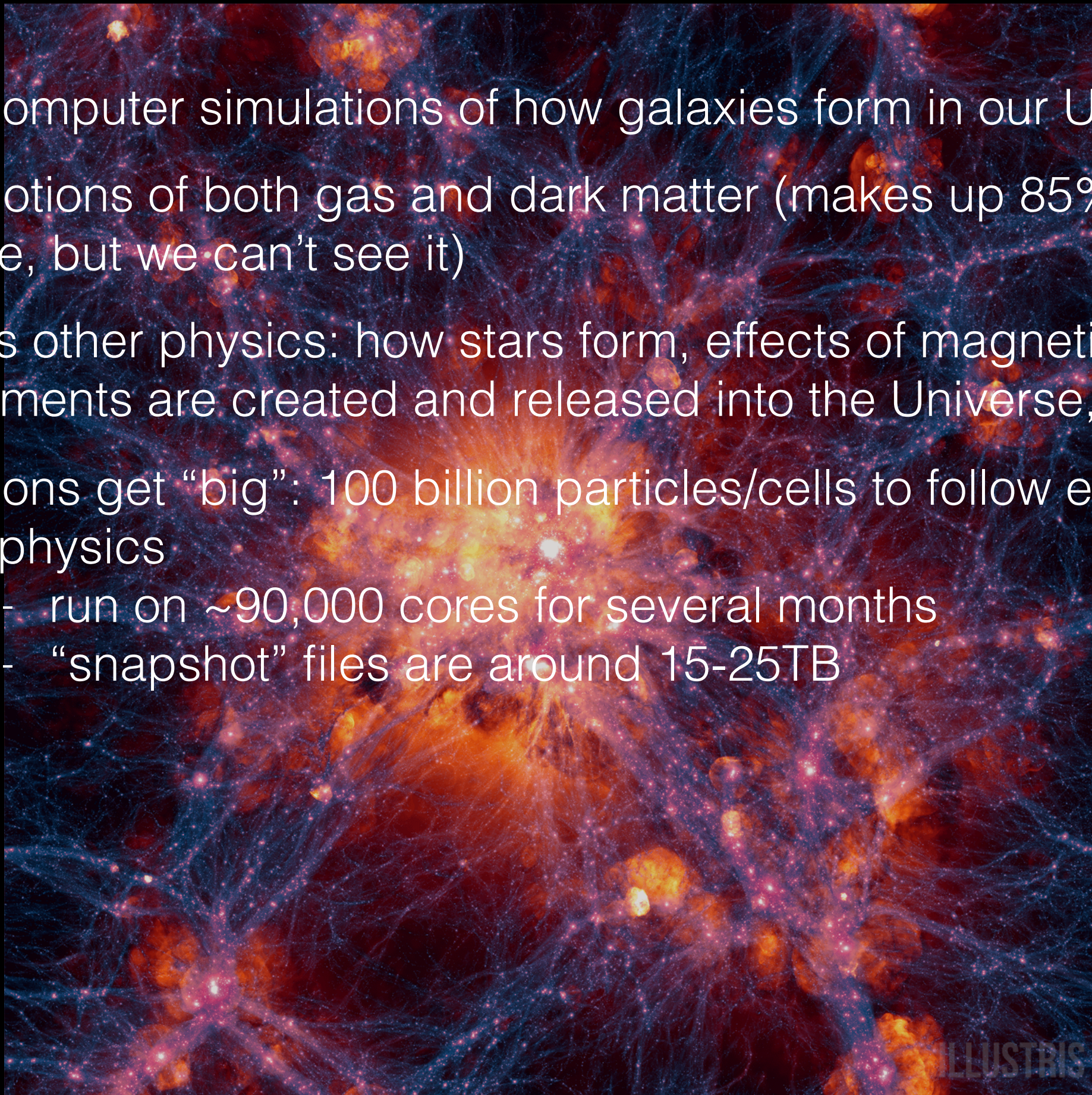


I'm particularly interested in how metals (stuff heavier than H & He) moves from its production sites (inside massive stars) to the larger galactic scales

ILLUSTRIS

Who are you and what do you do?

- ◆ Super computer simulations of how galaxies form in our Universe
- ◆ Track motions of both gas and dark matter (makes up 85% of the Universe, but we can't see it)
- ◆ Includes other physics: how stars form, effects of magnetic fields, how elements are created and released into the Universe, etc
- ◆ Simulations get “big”:
 - 100 billion particles/cells to follow each with its own physics
 - run on ~90,000 cores for several months
 - “snapshot” files are around 15-25TB



And now... some gratuitous movies!

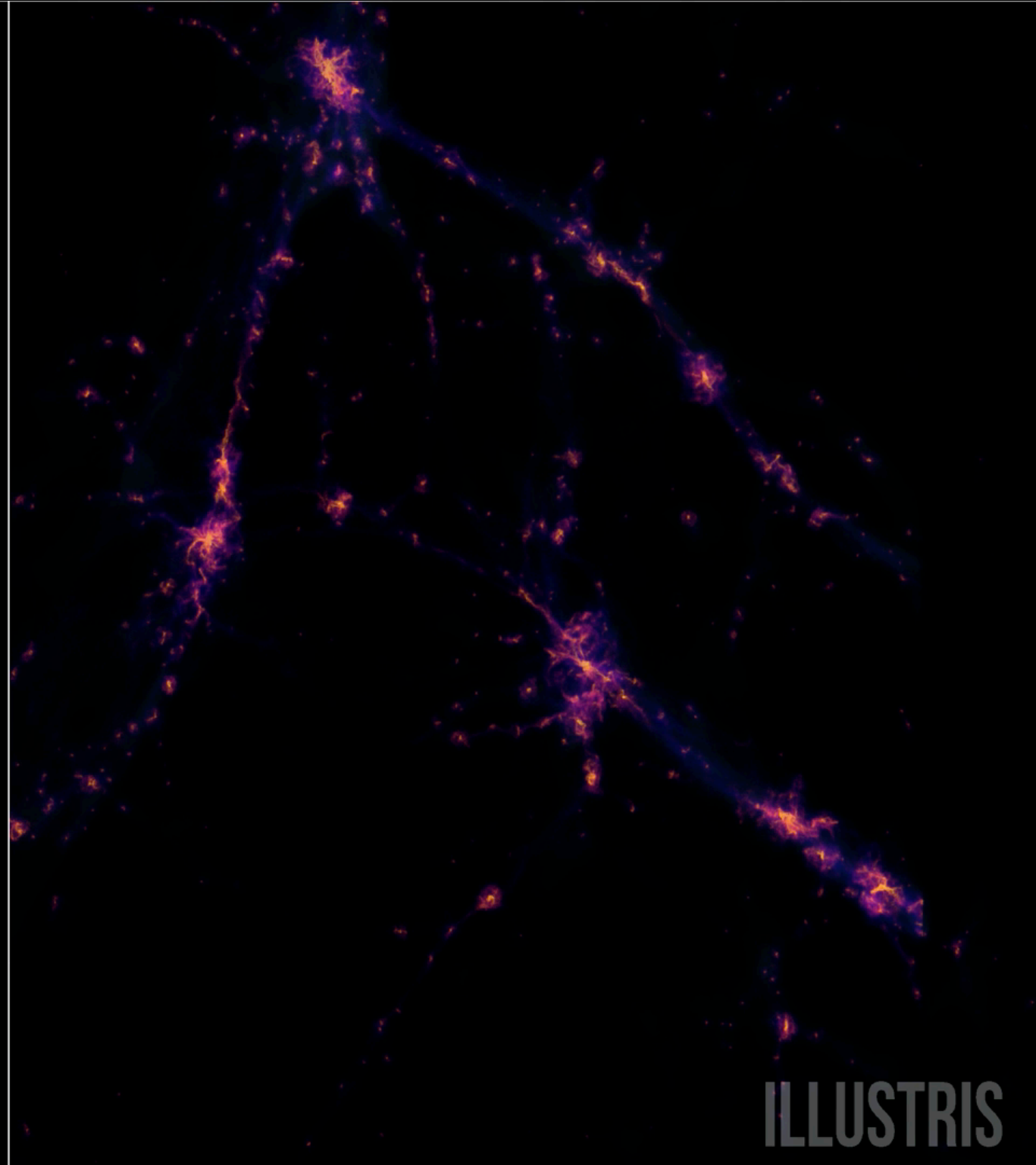
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$z=4.00$

$\log_{10}(M_*)=10.4$

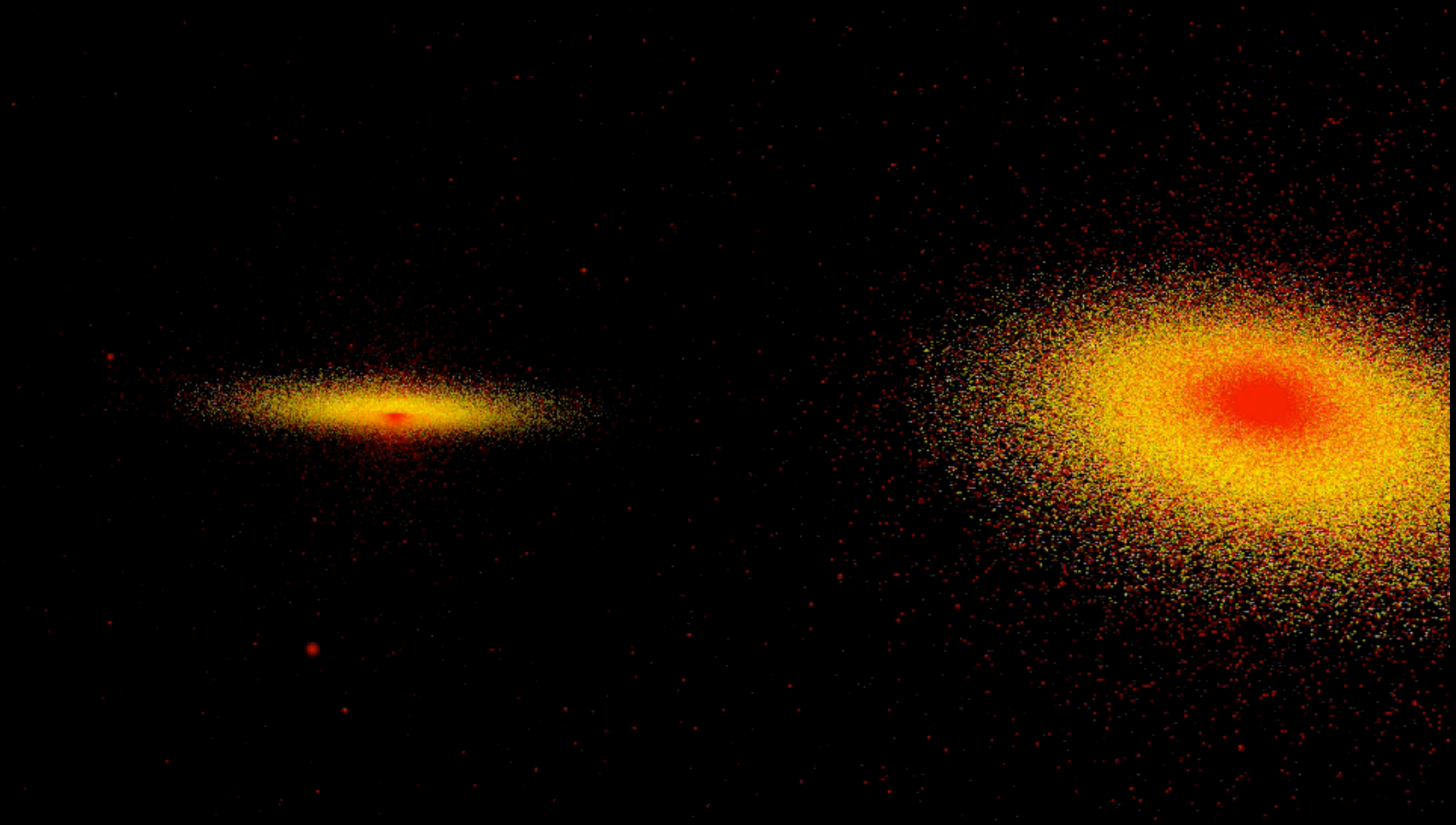
SFR=80.0

sSFR=3.07Gyr⁻¹



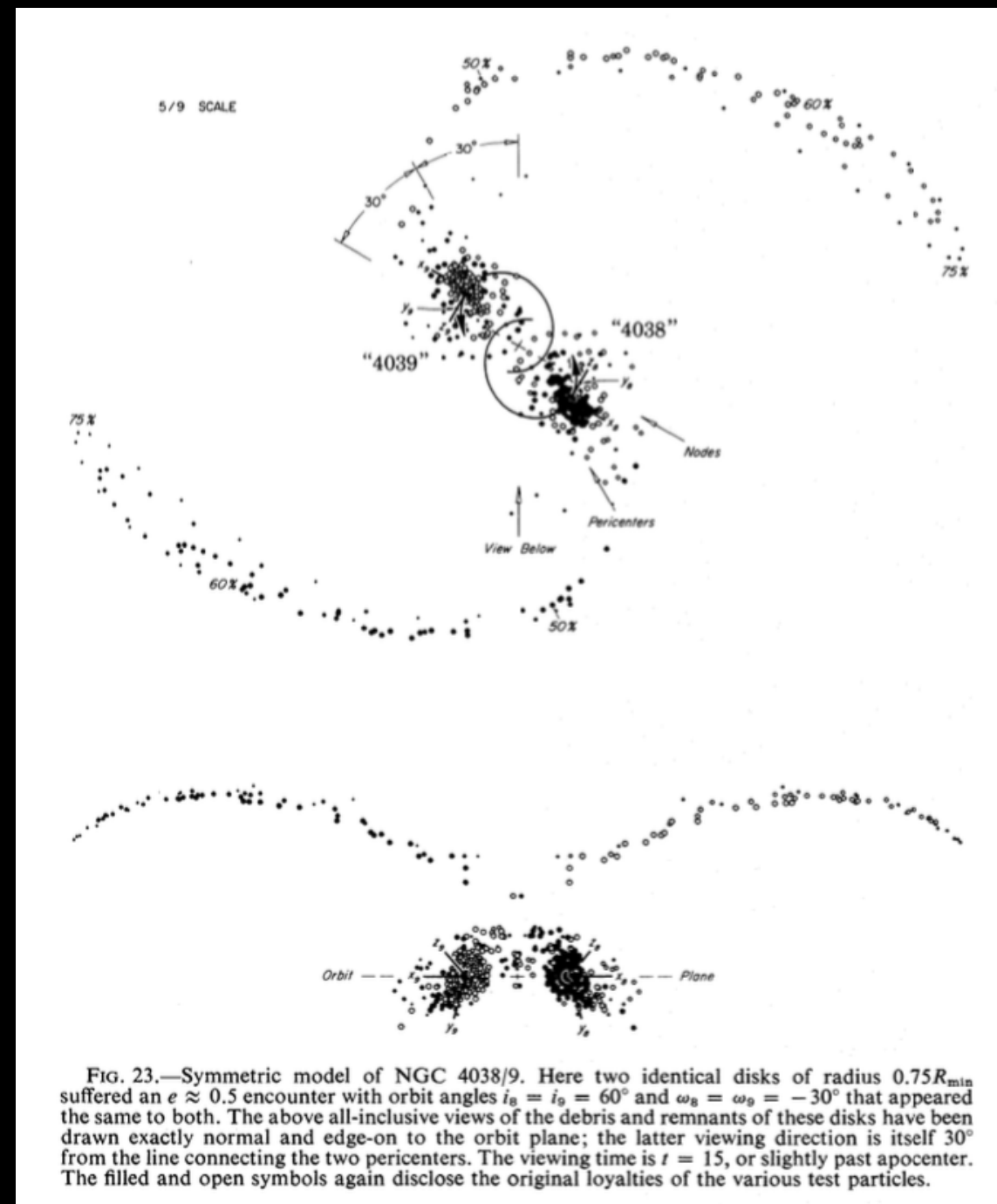
ILLUSTRIS

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~4 billion particles

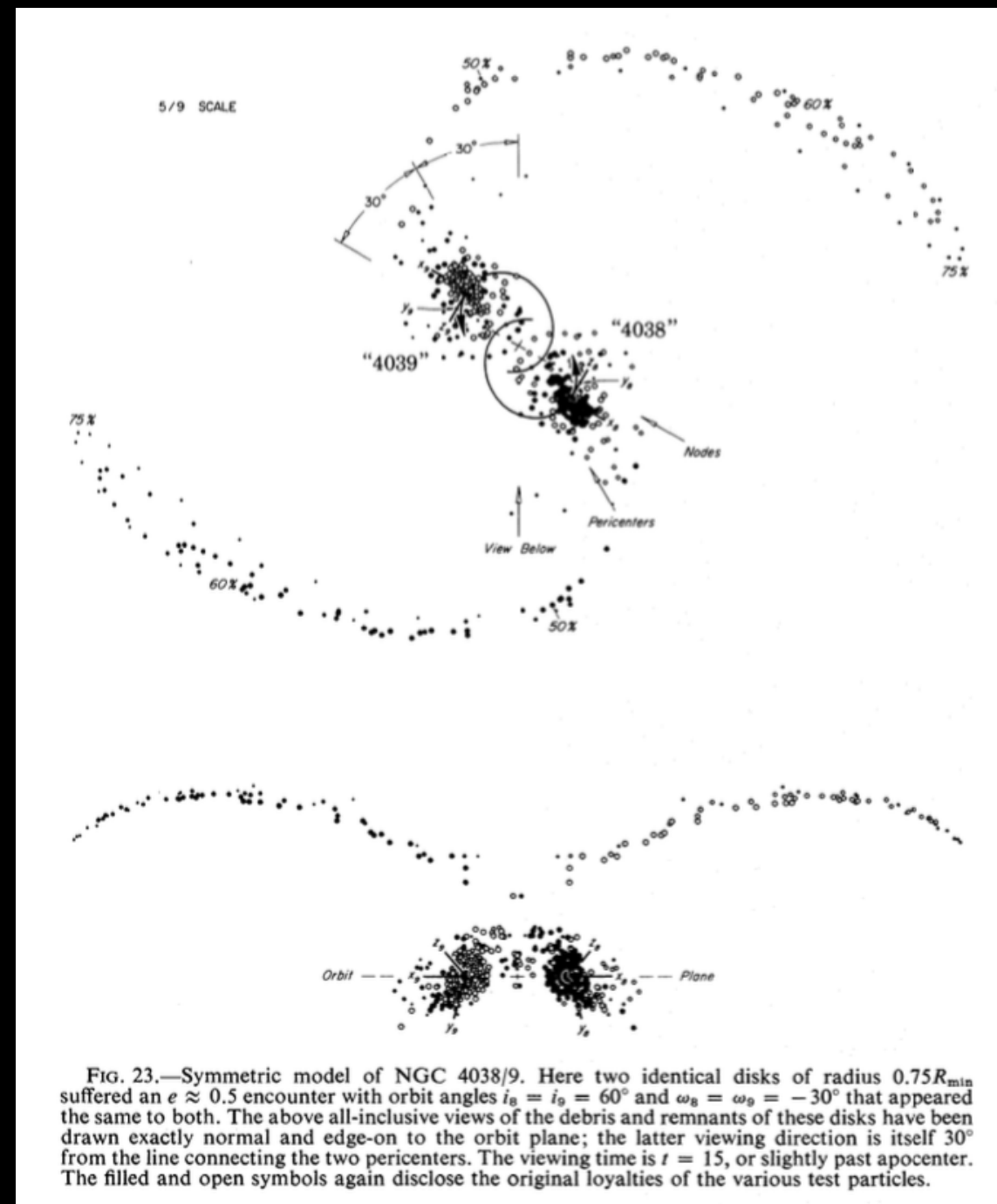
... Galaxy Mergers are an N-Body problem



Toomre & Toomre in the 1970's wanted to explain the observed tidal tails and bridges between galaxies - thought it might have to do with mergers.

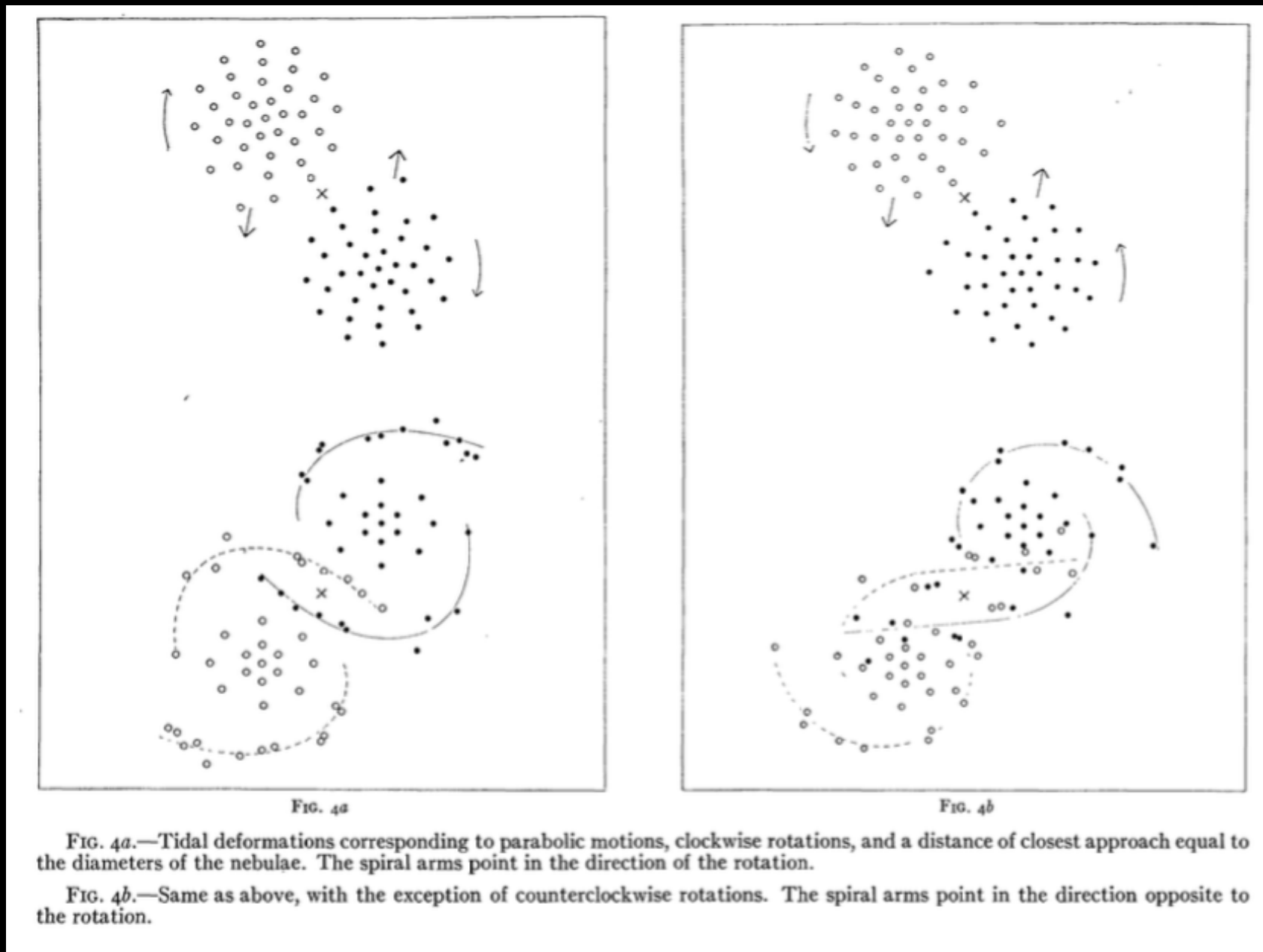
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~300 particles!



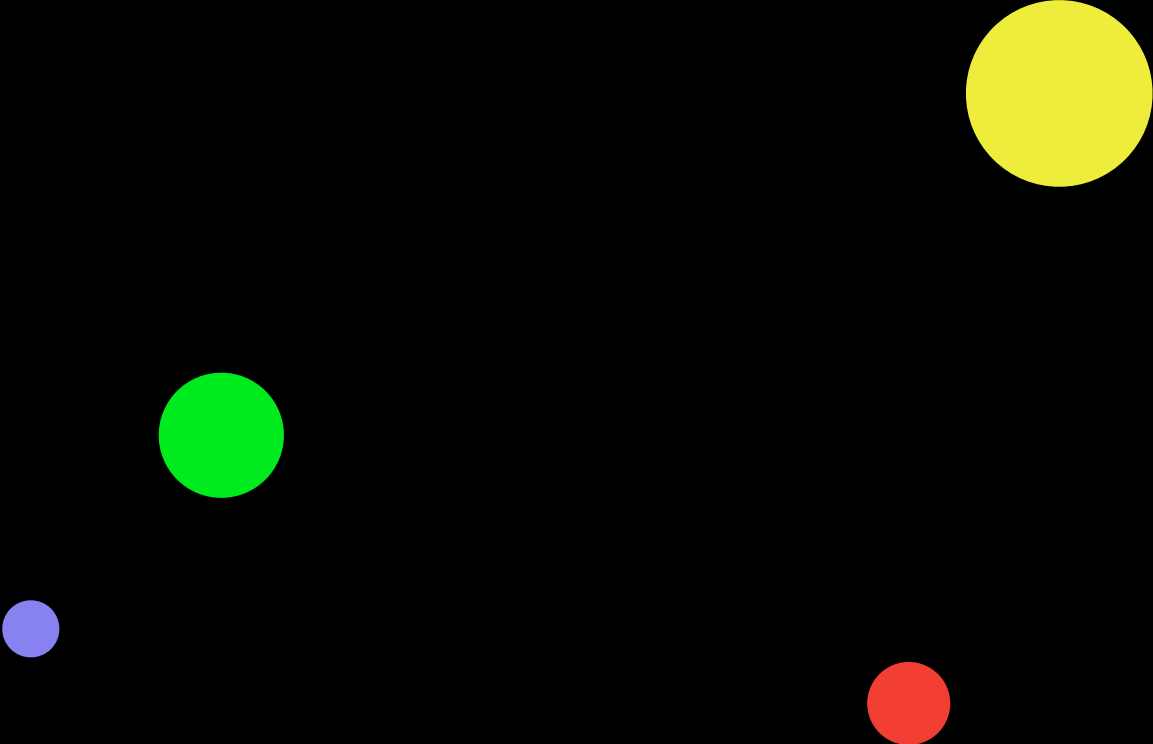
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... Galaxy Mergers are an N-Body problem



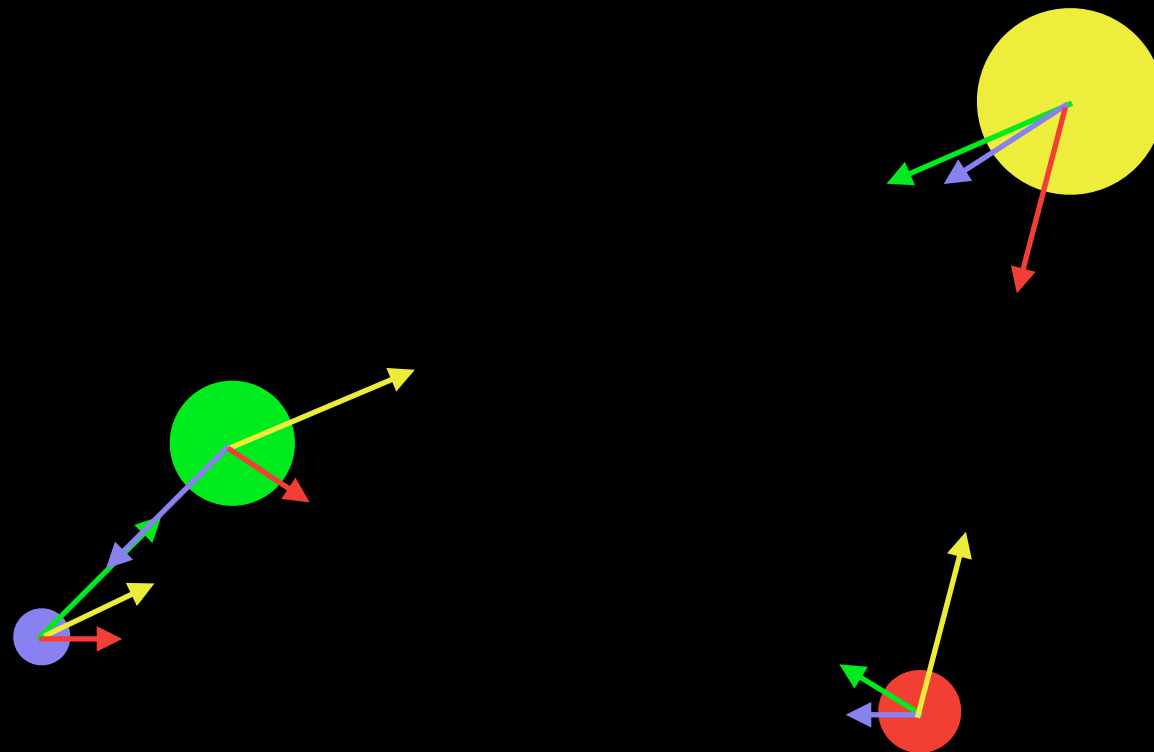
Cool bit of history: Holmberg 1941 did the N-body problem using overlapping lights and photocells to figure out density and backtrack out gravitational force between particles.

N-Body Simulations



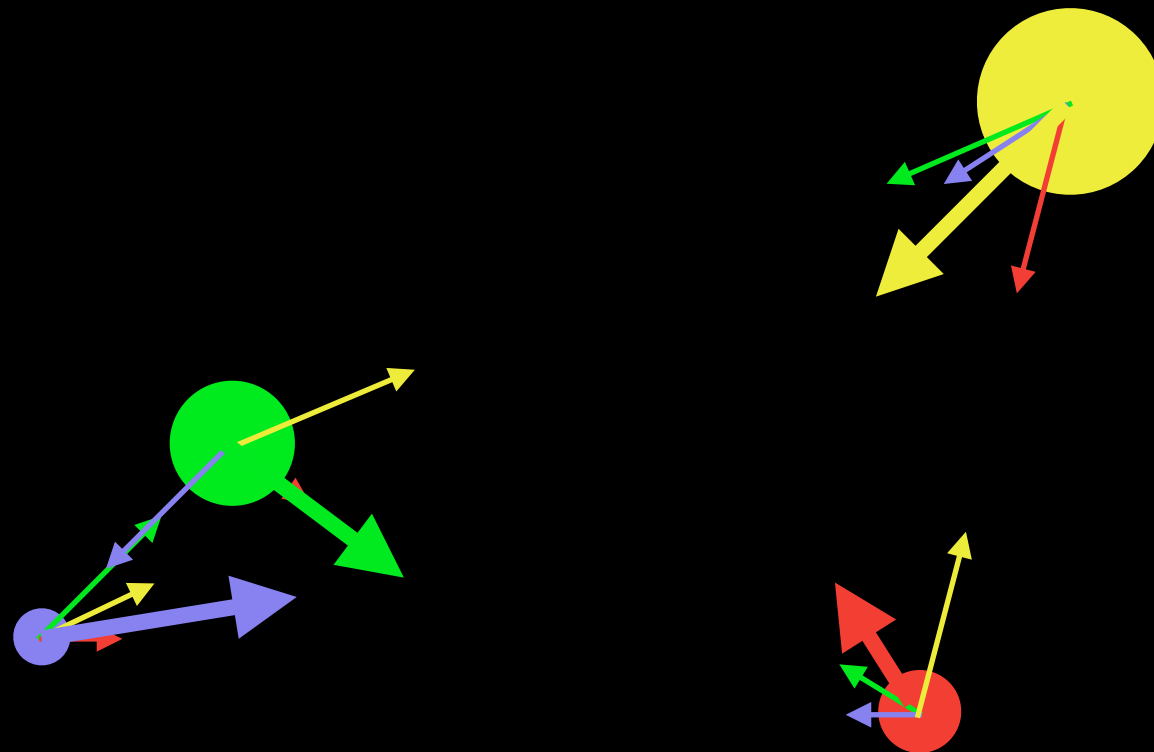
N-Body Simulations

For each particle you have to calculate the force exerted on it by each other particle



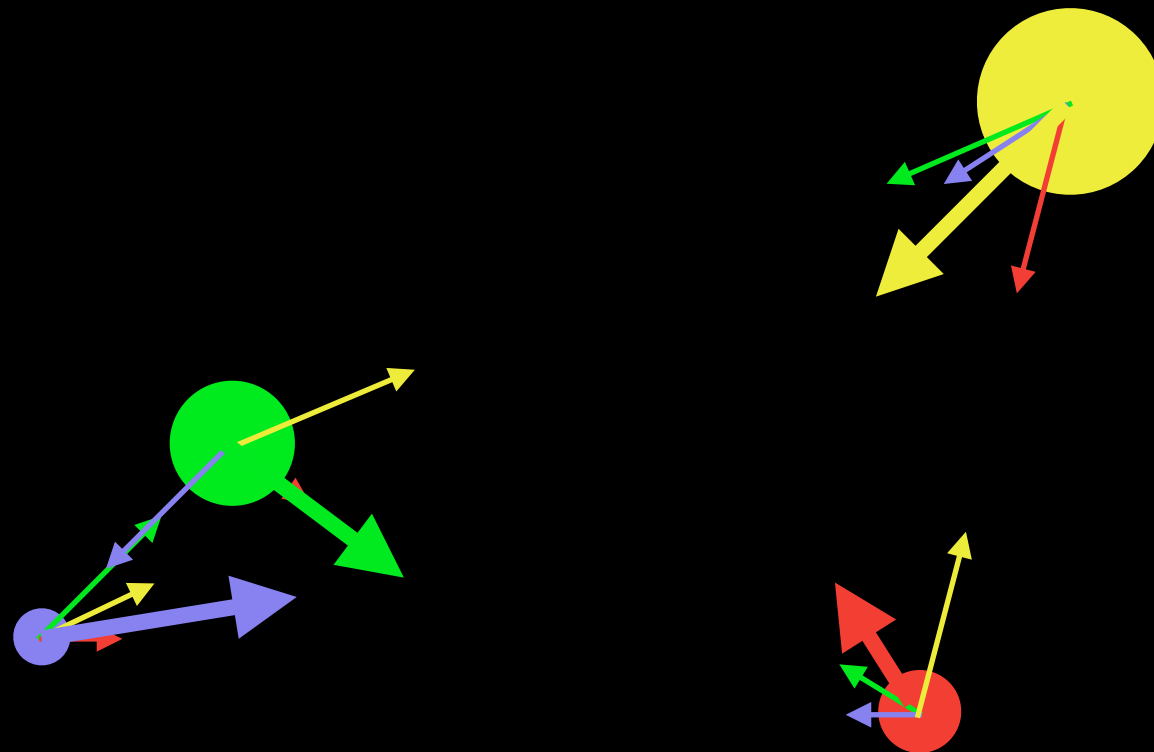
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N-Body Simulations

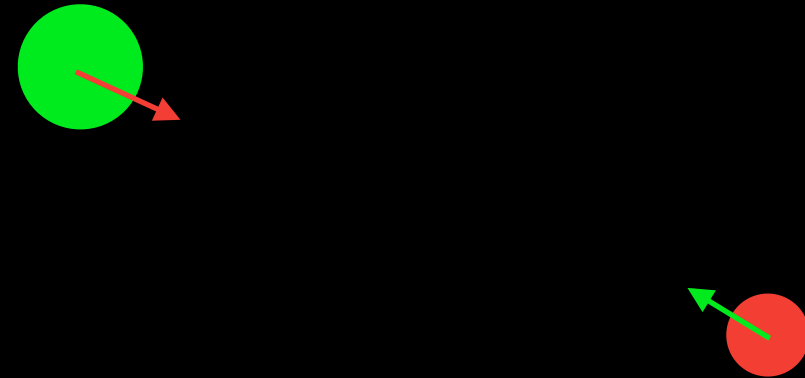
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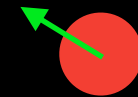
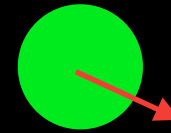
$$\mathbf{F}_i = \sum_{\substack{1 \leq j \leq N \\ j \neq i}} \mathbf{f}_{ij} = Gm_i \cdot \sum_{\substack{1 \leq j \leq N \\ j \neq i}} \frac{m_j \mathbf{r}_{ij}}{\|\mathbf{r}_{ij}\|^3}$$

Force between any set of particles $\sim (M \times m)/r^2$

N-Body Simulations: The 2 Body problem



N-Body Simulations: The 2 Body problem



$$\frac{\vec{F}_{1,2}}{m_1} = \vec{a}_1 = \frac{d^2\vec{r}_1}{dt^2}$$

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N-Body Simulations: The 2 Body problem

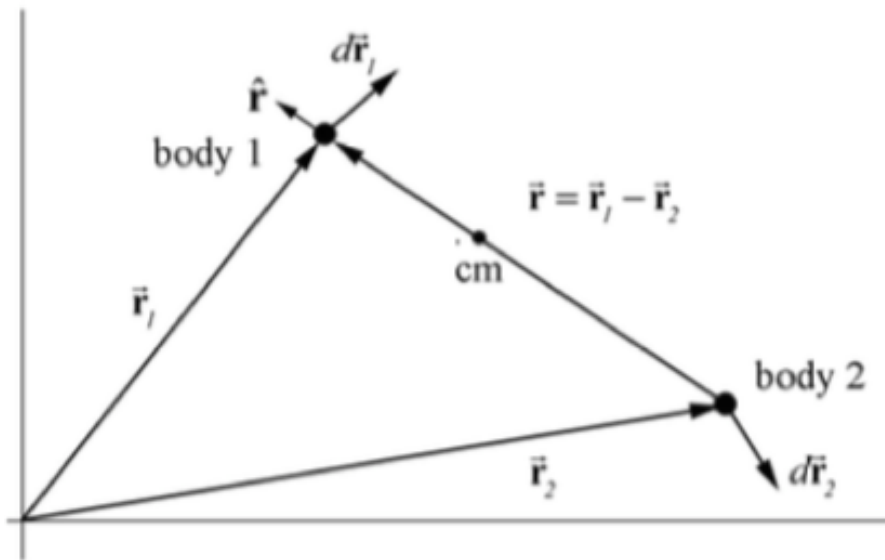
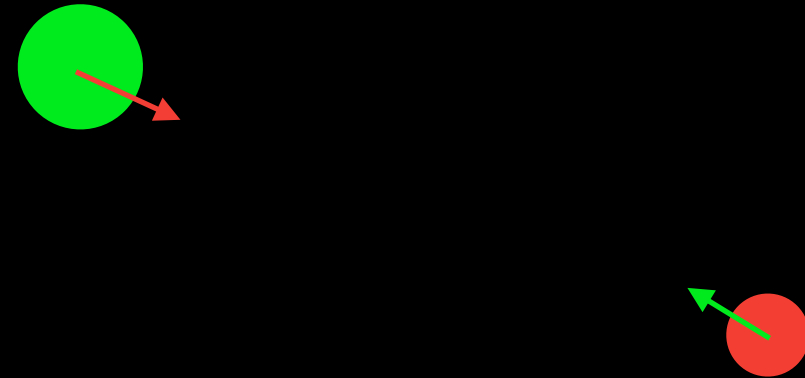
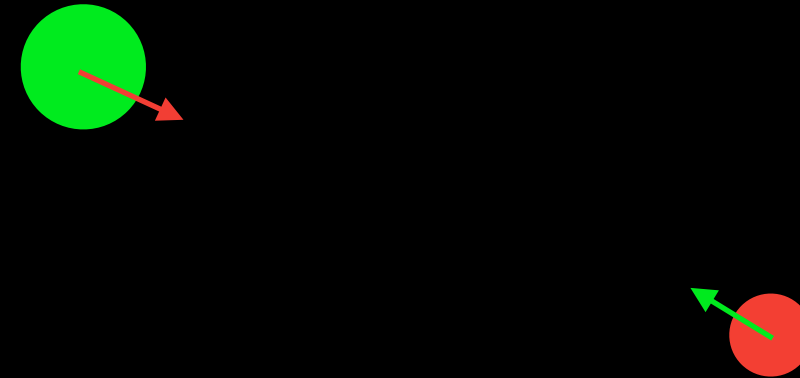
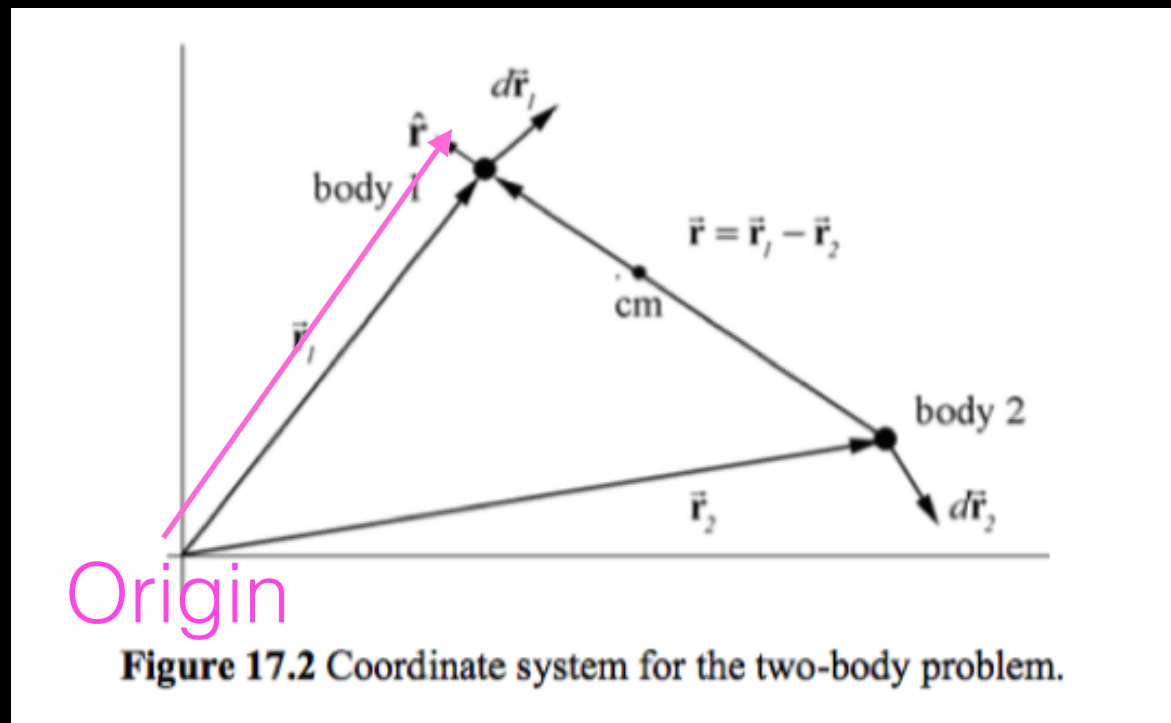


Figure 17.2 Coordinate system for the two-body problem.



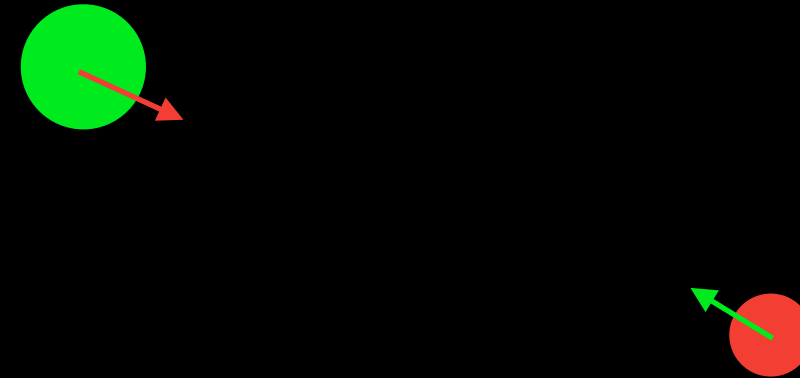
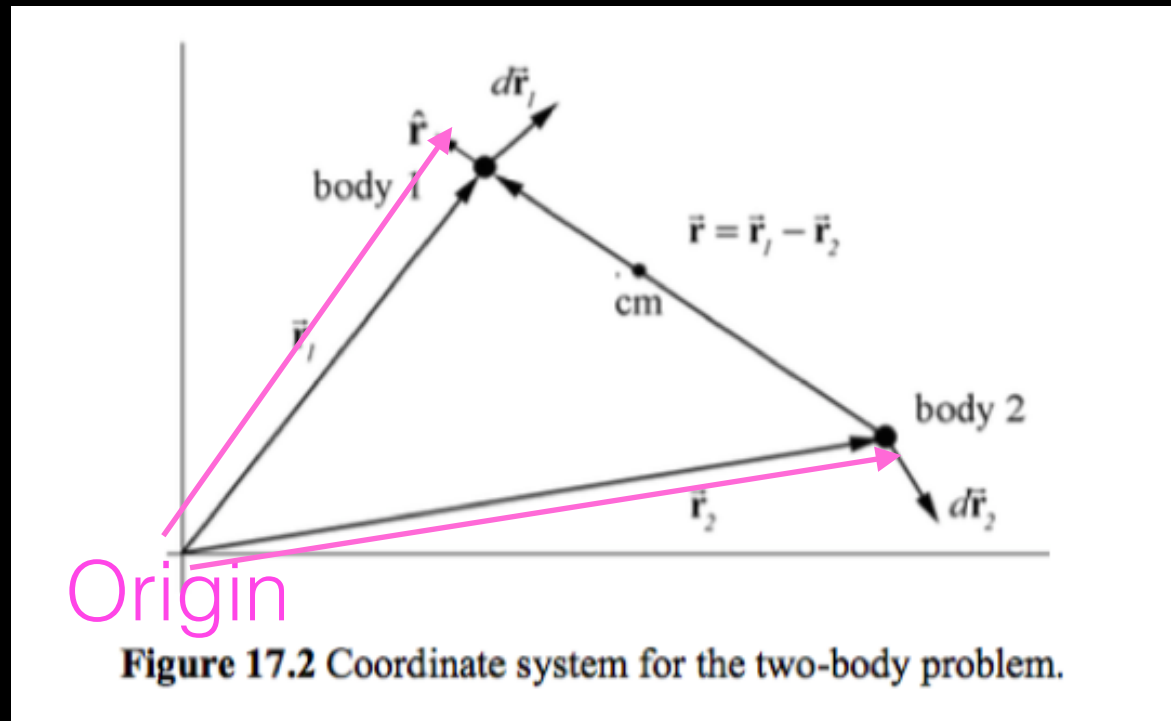
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N-Body Simulations: The 2 Body problem



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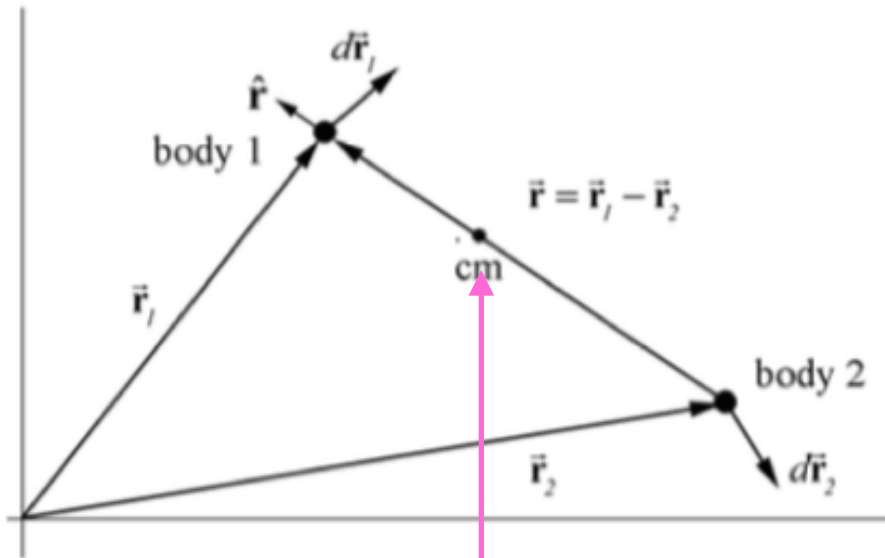
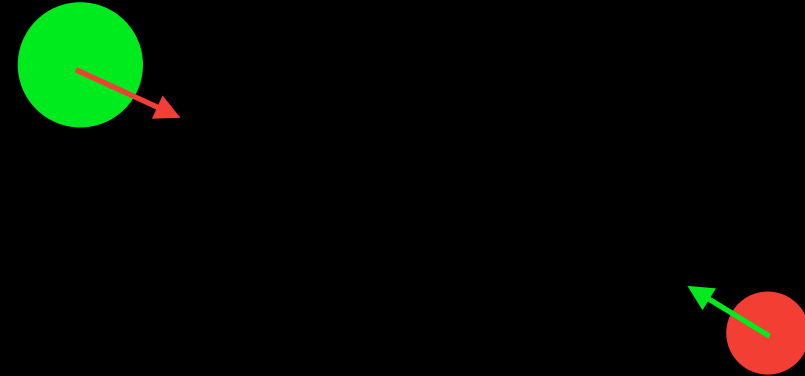


Figure 17.2 Coordinate system for the two-body problem.

center of mass = balance point



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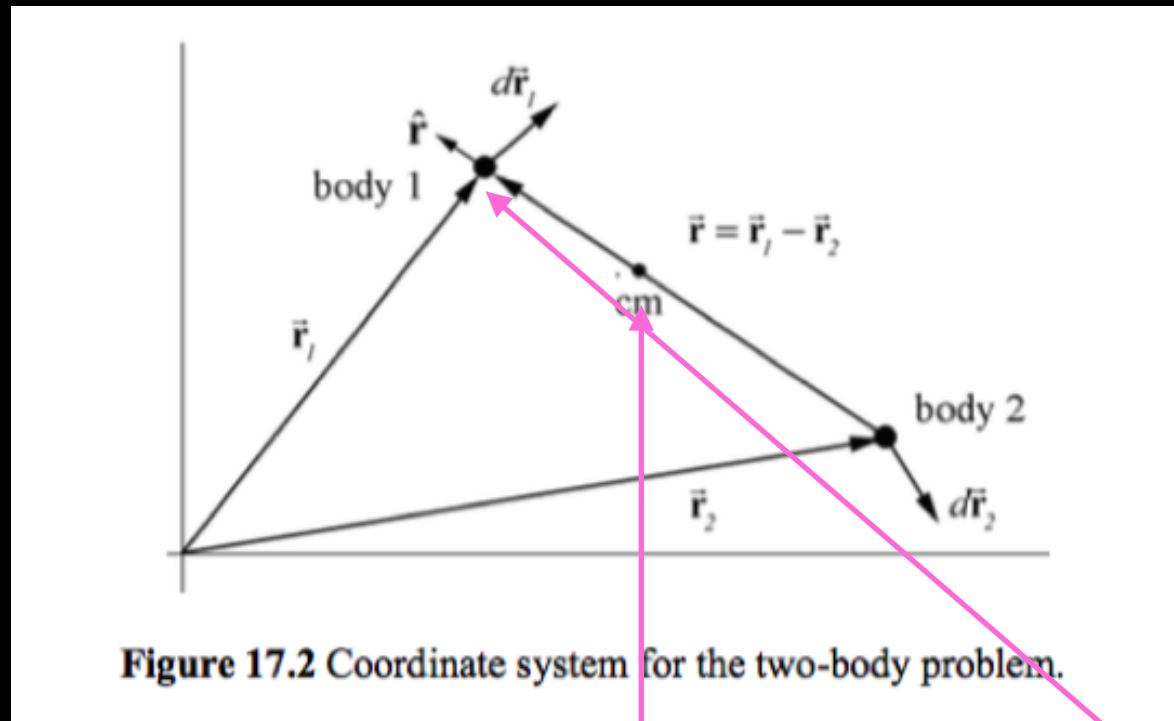
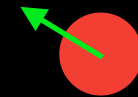
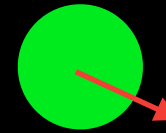


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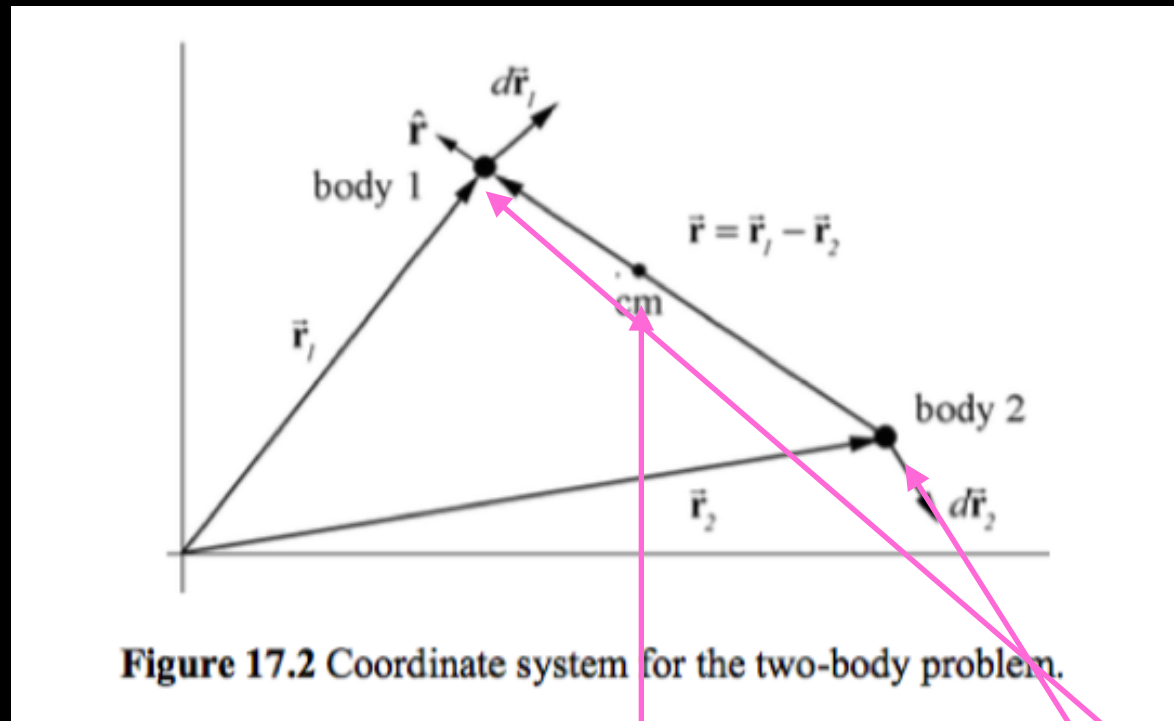
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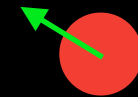
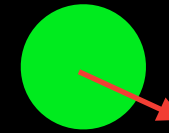
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body 1 experiences an acceleration from the gravitational force between it and body 2

N-Body Simulations: The 2 Body problem



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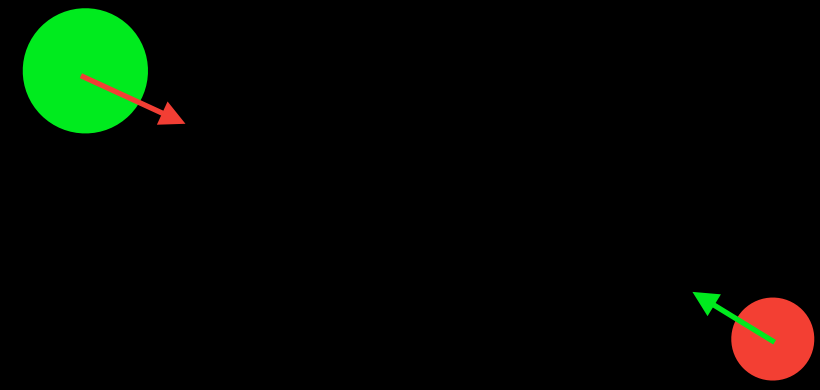
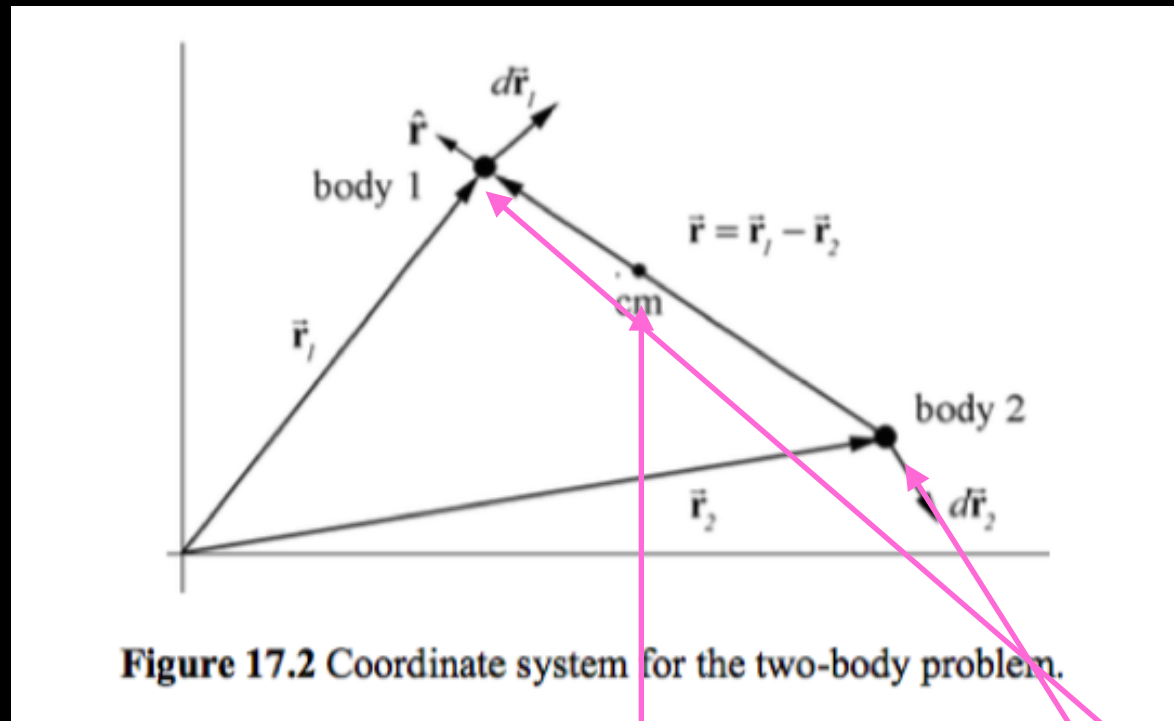
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body 1 experiences an acceleration from the gravitational force between it and body 2

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N-Body Simulations: The 2 Body problem



center of mass = balance point

Where gravity depends on their masses and the distance between them.

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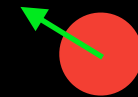
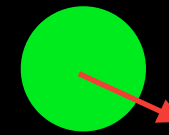
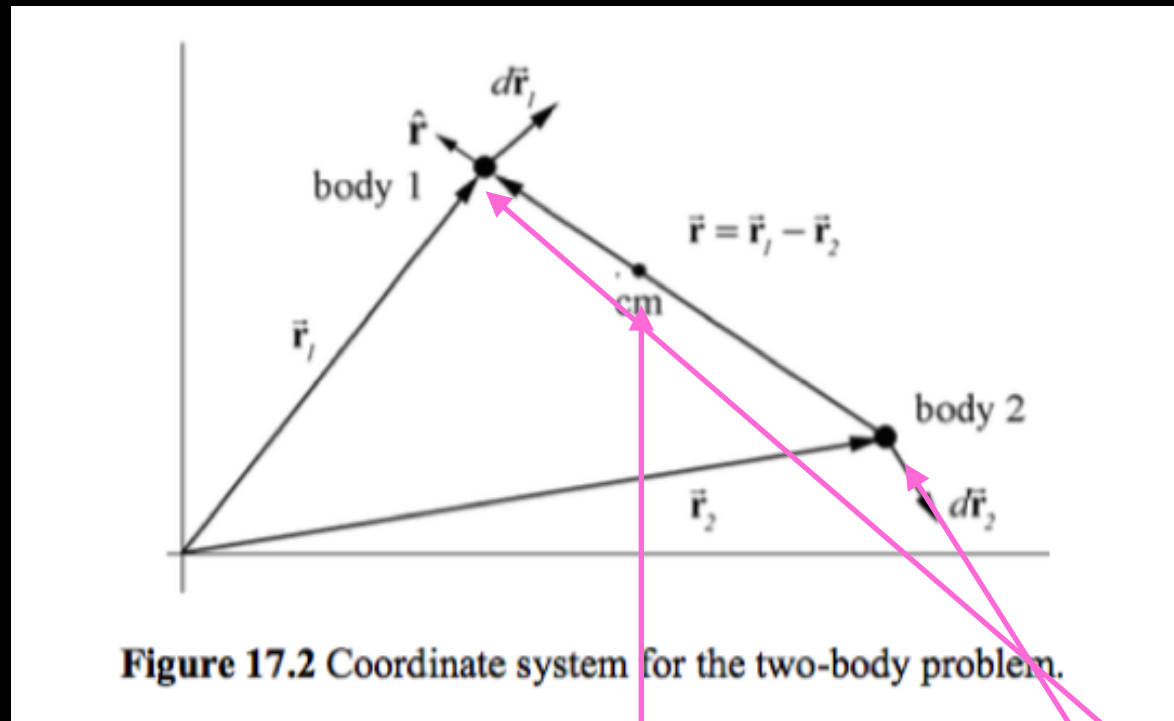
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body 1 experiences an acceleration from the gravitational force between it and body 2

body 2 experiences an acceleration from the gravitational force between it and body 1

N-Body Simulations: The 2 Body problem



center of mass = balance point

Where gravity depends on their masses and the distance between them.

The 2nd derivative of a position depends on the position through the force of gravity - **Differential Equation!**

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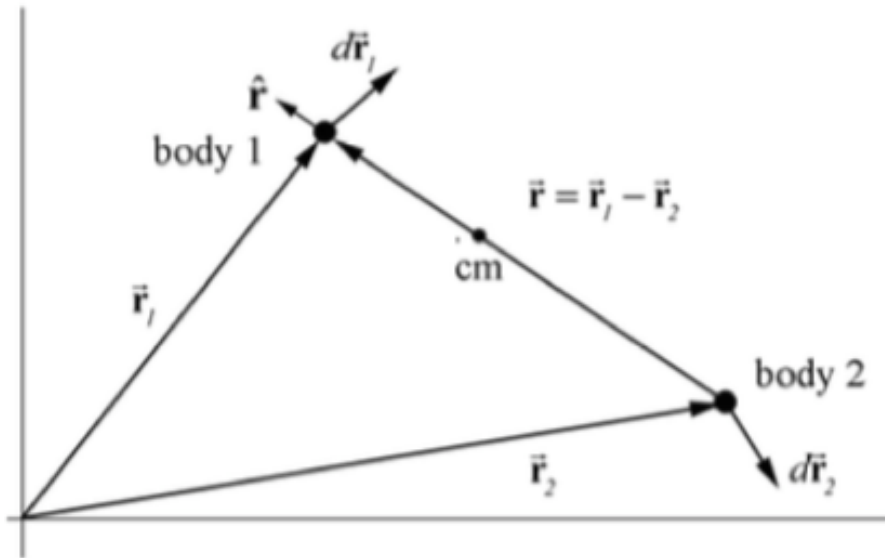
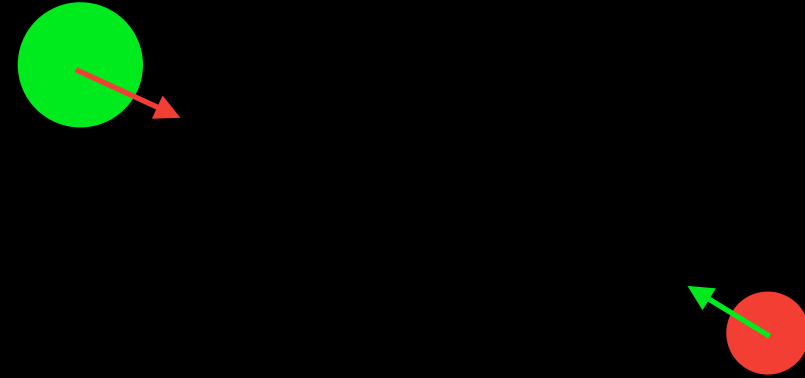


Figure 17.2 Coordinate system for the two-body problem.



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N-Body Simulations: The 2 Body problem

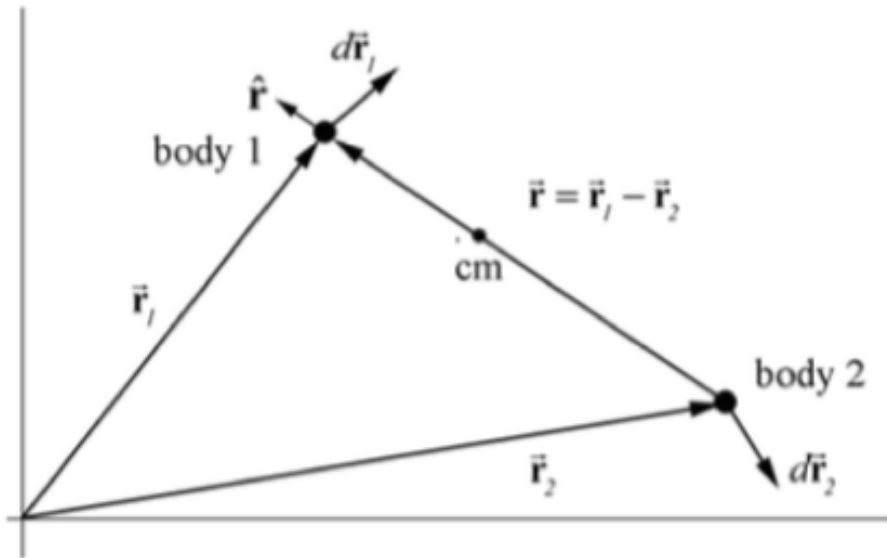
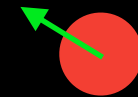
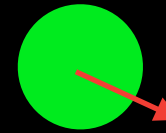


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A BUNCH OF MATH
(ask Jenny!)



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N-Body Simulations: The 2 Body problem

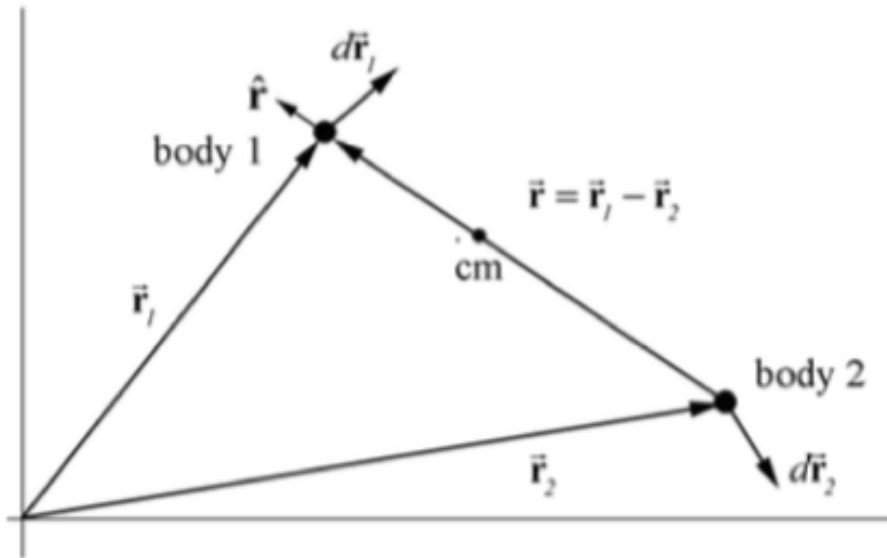
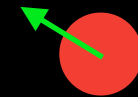
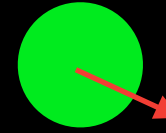
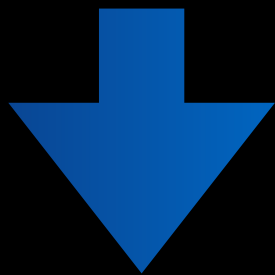


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$$r = \frac{a(1 - e^2)}{1 + e \cos \theta}$$

$$\begin{aligned} \frac{\vec{F}_{1,2}}{m_1} &= \vec{a}_1 = \frac{d^2 \vec{r}_1}{dt^2} \\ \frac{\vec{F}_{2,1}}{m_2} &= \vec{a}_2 = \frac{d^2 \vec{r}_2}{dt^2} \\ \vec{F}_{1,2} &= -\vec{F}_{2,1} = -G \frac{m_1 m_2}{|\vec{r}_1 - \vec{r}_2|^2} \times \frac{\vec{r}_1 - \vec{r}_2}{|\vec{r}_1 - \vec{r}_2|} \end{aligned}$$

N-Body Simulations: The 2 Body problem

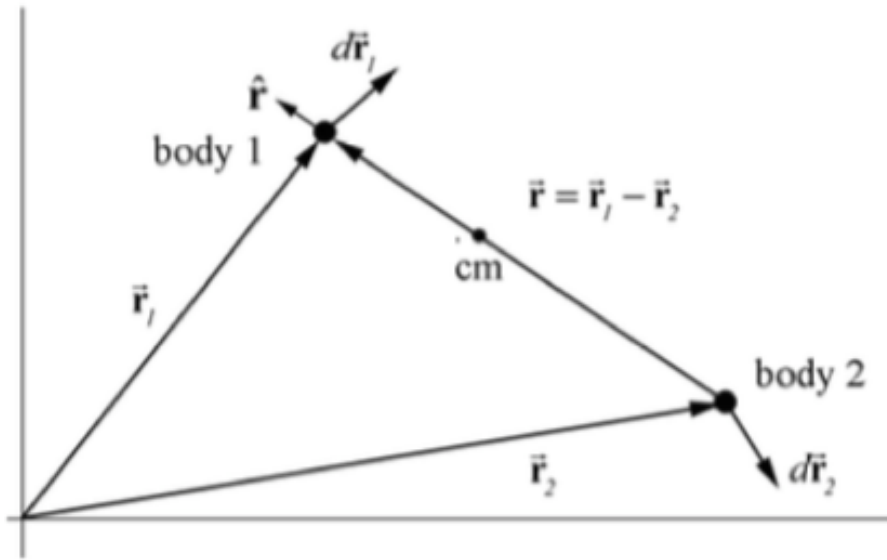
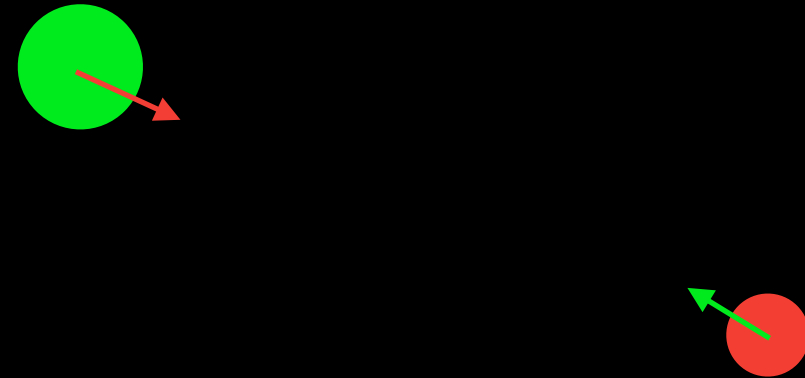


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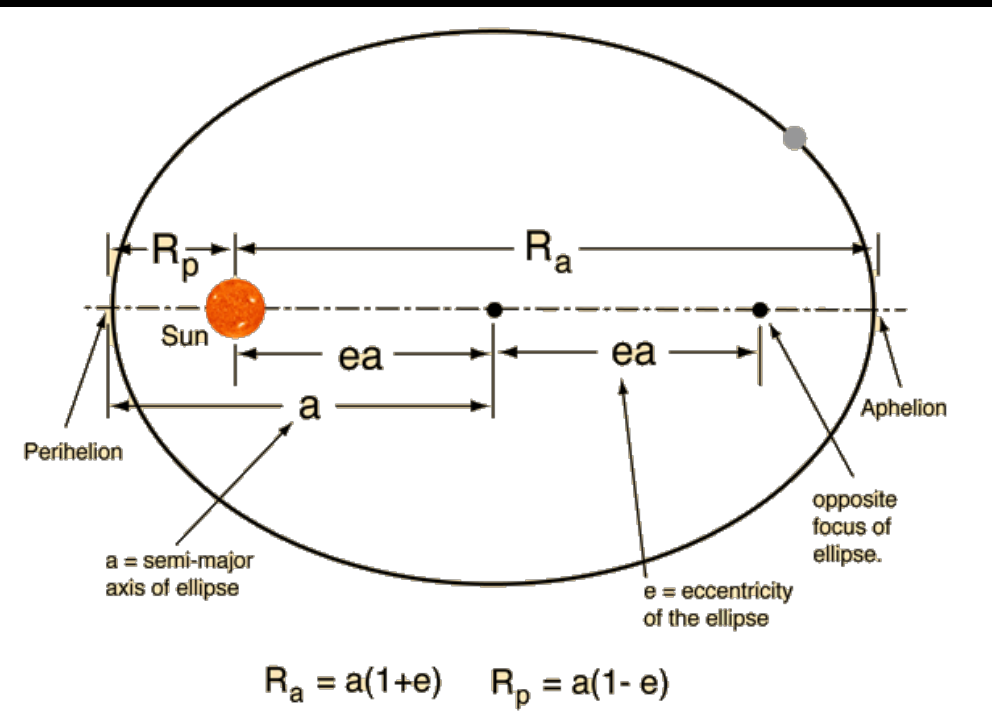
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N-Body Simulations: The 2 Body problem

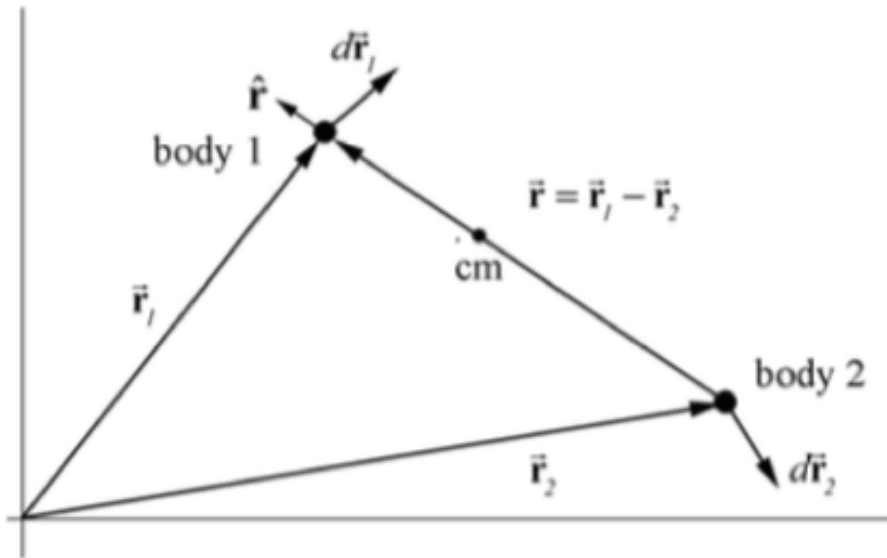
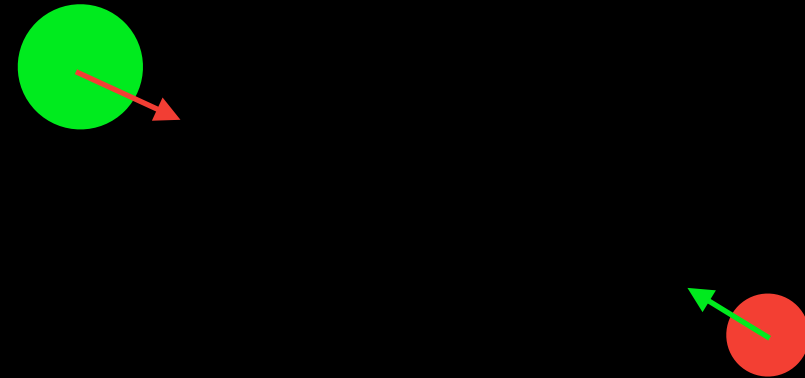


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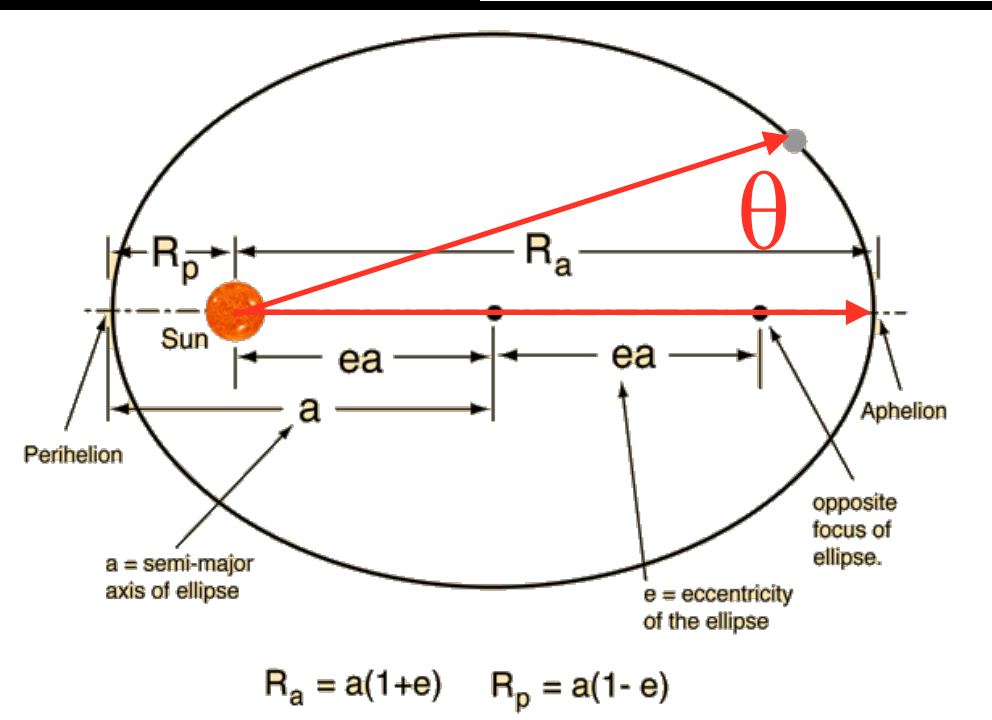
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N-Body Simulations: The 2 Body problem

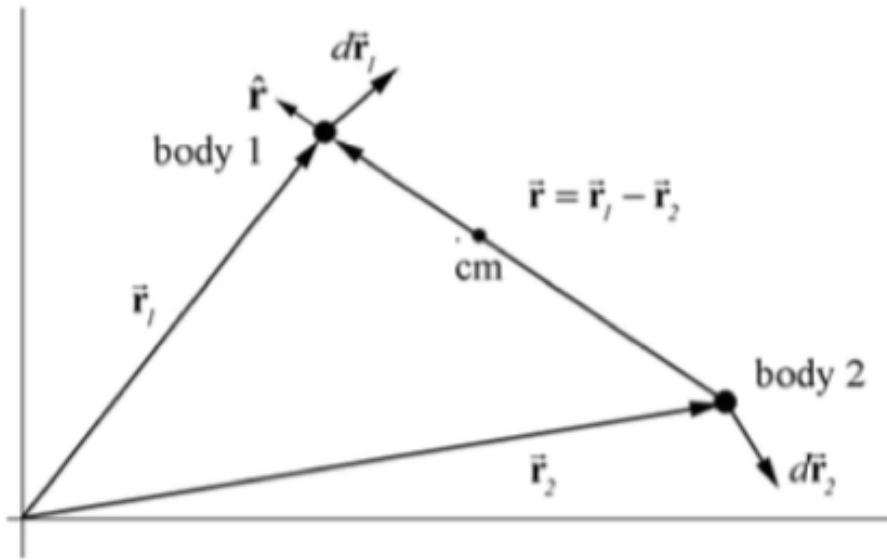
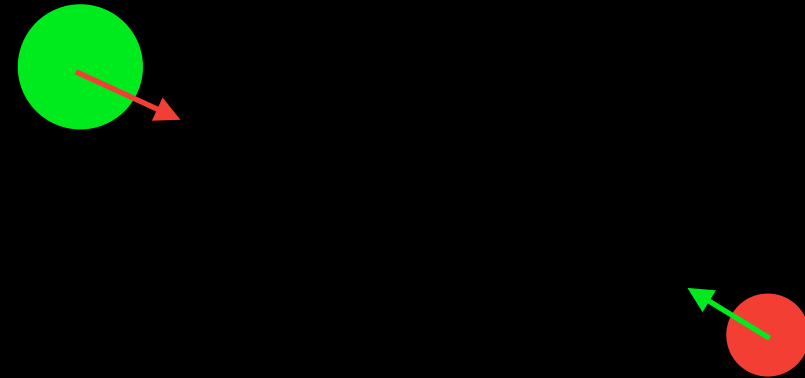


Figure 17.2 Coordinate system for the two-body problem.



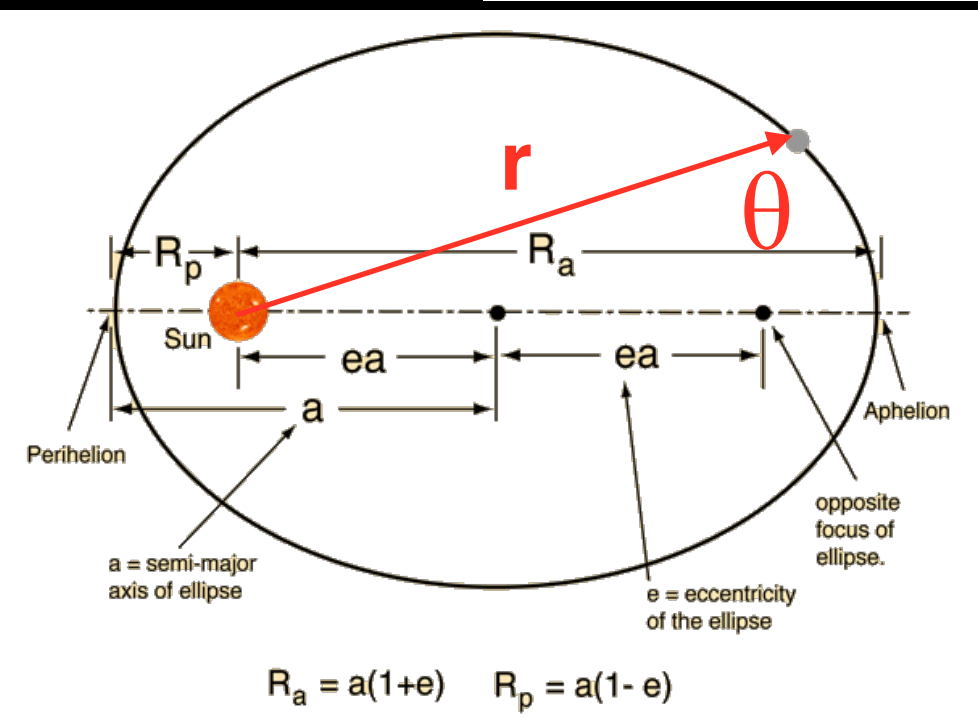
A BUNCH OF MATH
(ask Jenny!)

$$\frac{\vec{F}_{1,2}}{m_1} = \vec{a}_1 = \frac{d^2 \vec{r}_1}{dt^2}$$

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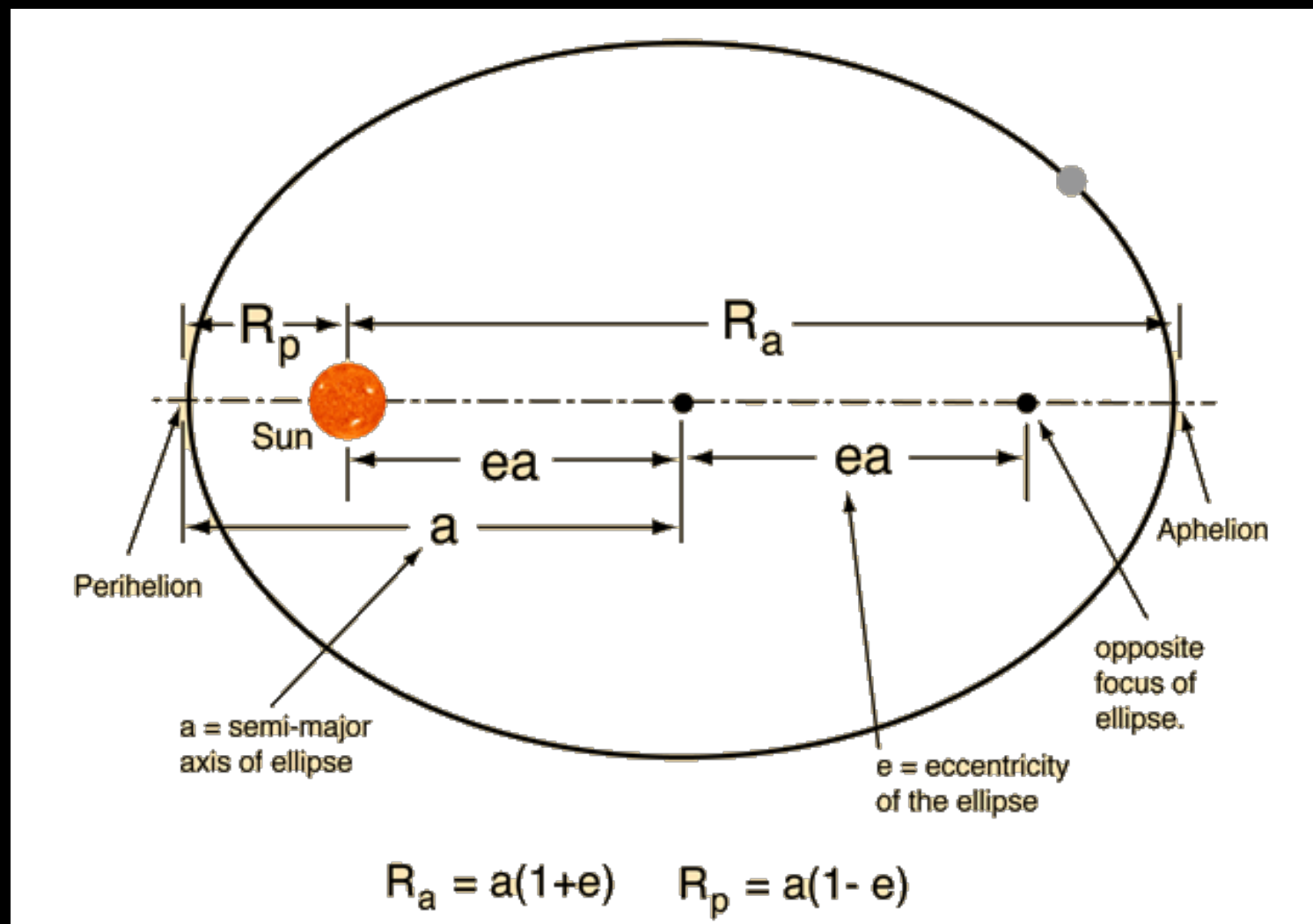
$$\vec{F}_{1,2} = -\vec{F}_{2,1} = -G \frac{m_1 m_2}{|\vec{r}_1 - \vec{r}_2|^2} \times \frac{\vec{r}_1 - \vec{r}_2}{|\vec{r}_1 - \vec{r}_2|}$$

$$r = \frac{a(1 - e^2)}{1 + e \cos \theta}$$



N-Body Simulations: The 2 Body problem

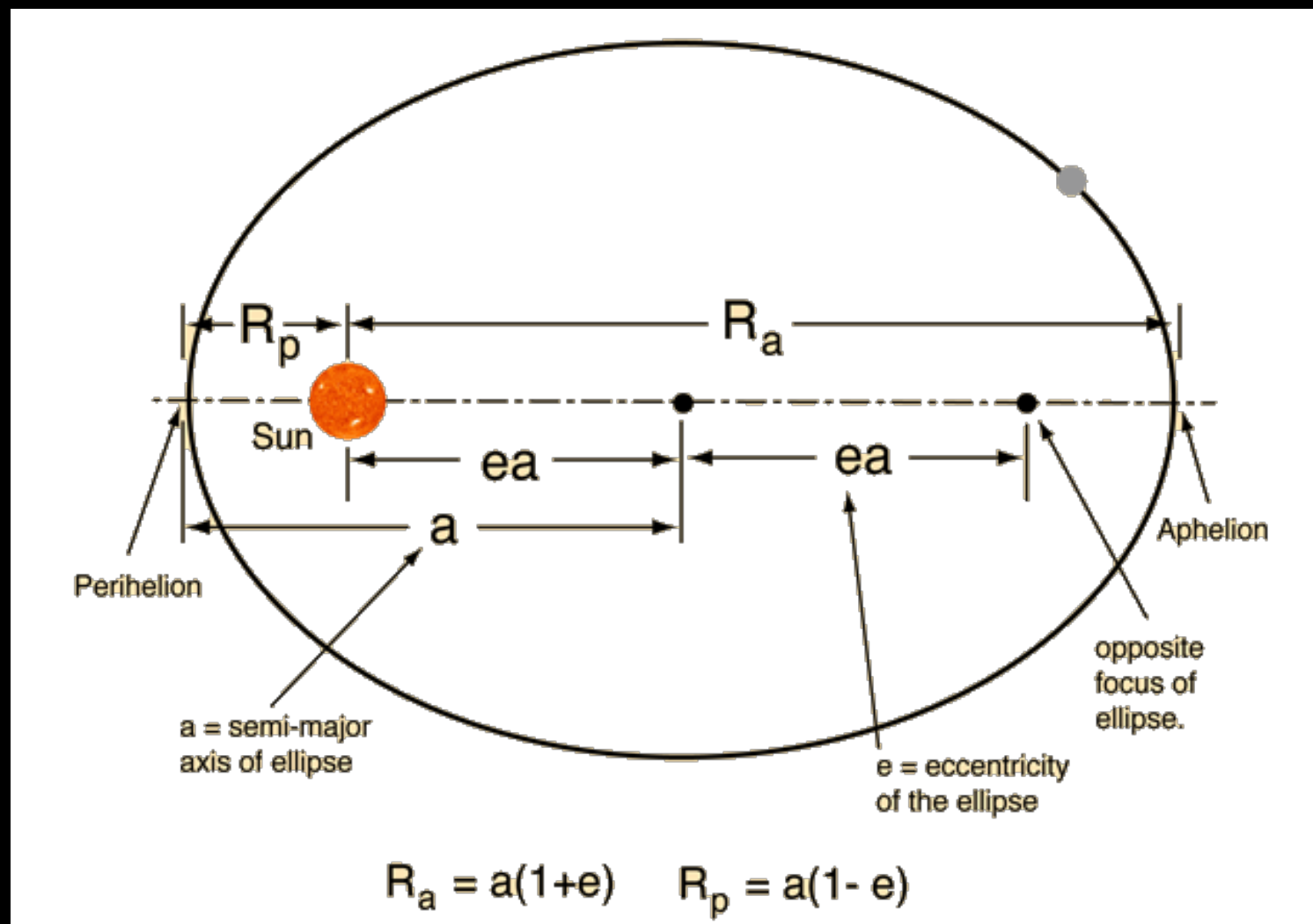
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Bunch of relations between: e , a , R_a , R_p , etc (more info in links online)

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One super important one is Kepler's 3rd Law

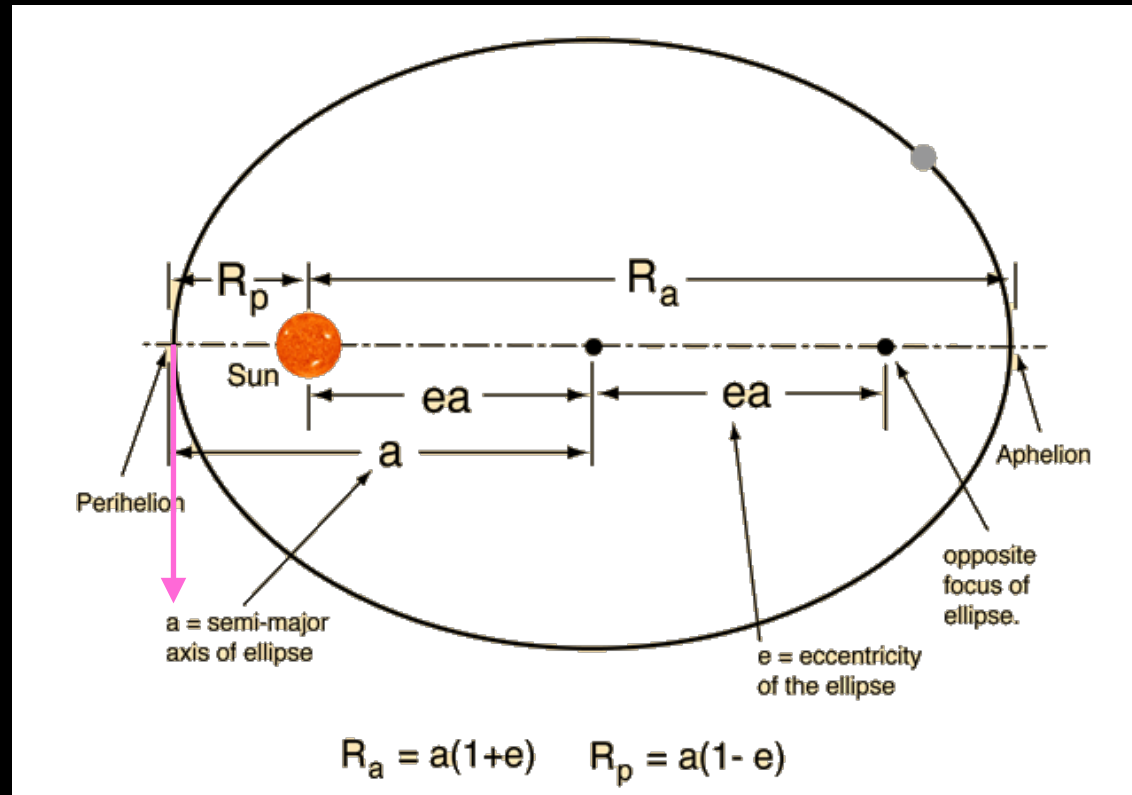
$$\frac{P^2}{a^3} = \frac{4\pi^2}{G(M + m)}$$

Period = time to go around once

Bunch of relations between: e , a , R_a , R_p , etc (more info in links online)

N-Body Simulations: The 2 Body problem

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$$\frac{P^2}{a^3} = \frac{4\pi^2}{G(M+m)}$$

Some conserved quantities:

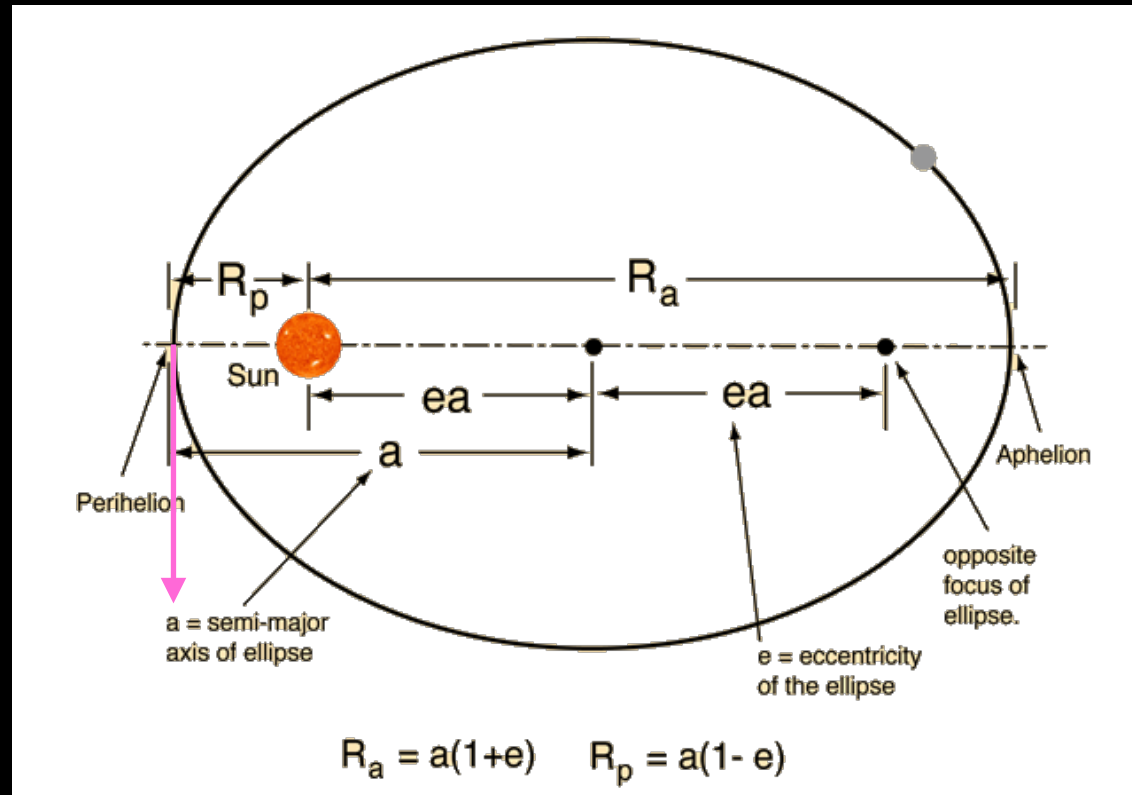
$$E = -\frac{Gm_1m_2}{2a}$$

$$\vec{L} = m_1 \vec{R}_{P,1} \times \vec{v}_{P,1} + m_2 \vec{R}_{P,2} \times \vec{v}_{P,2}$$

Derivations linked online! See Jenny too!

N-Body Simulations: The 2 Body problem

$$r = \frac{a(1 - e^2)}{1 + e \cos \theta}$$



One more thing about e :

circular orbit for $e = 0$

elliptical orbit for $0 < e < 1$

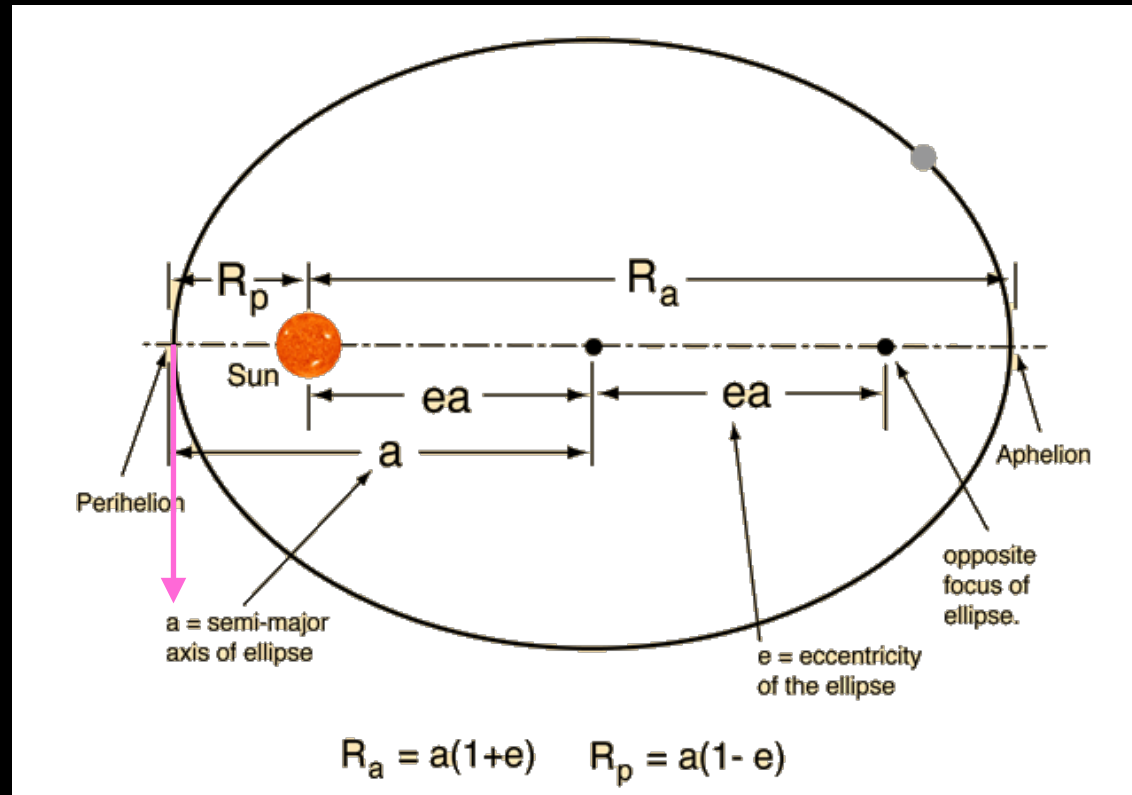
parabolic trajectory for $e = 1$ **“bound”**

hyperbolic trajectory for $e > 1$ **unbound**

bound

N-Body Simulations: The 2 Body problem

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circular orbit for $e = 0$

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parabolic trajectory for $e = 1$

hyperbolic trajectory for $e > 1$

bound

“bound”

unbound

N-Body Simulations: Start with 2 Bodies

```
import numpy as np
import matplotlib.pyplot as plt

# mass of particle 1 in solar masses
m1 = 1.0
# mass of particle 2 in jupiter masses
m2 = 1.0
# distance of m2 at closest approach (pericenter)
rp = 1.0 # in AU
# velocity of m2 at this closest approach distance
# we assume vp of the larger mass (m1) is negligible
vp = 35.0 # in km/s

# analytically here are the constants we need to define to solve:
ecc = rp*vp*vp/(G*(m1+m2)) - 1.0
a = rp/(1.0 - ecc)

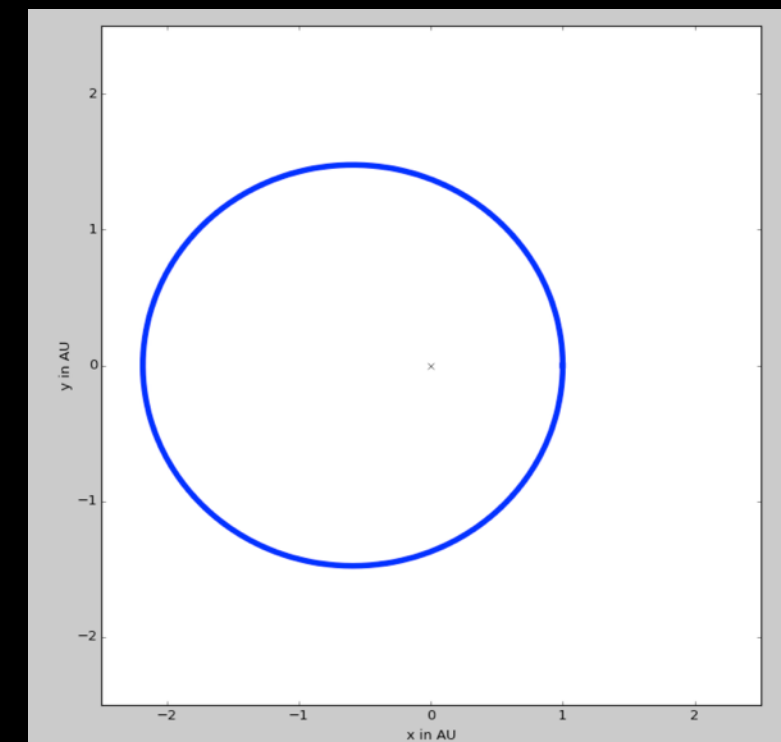
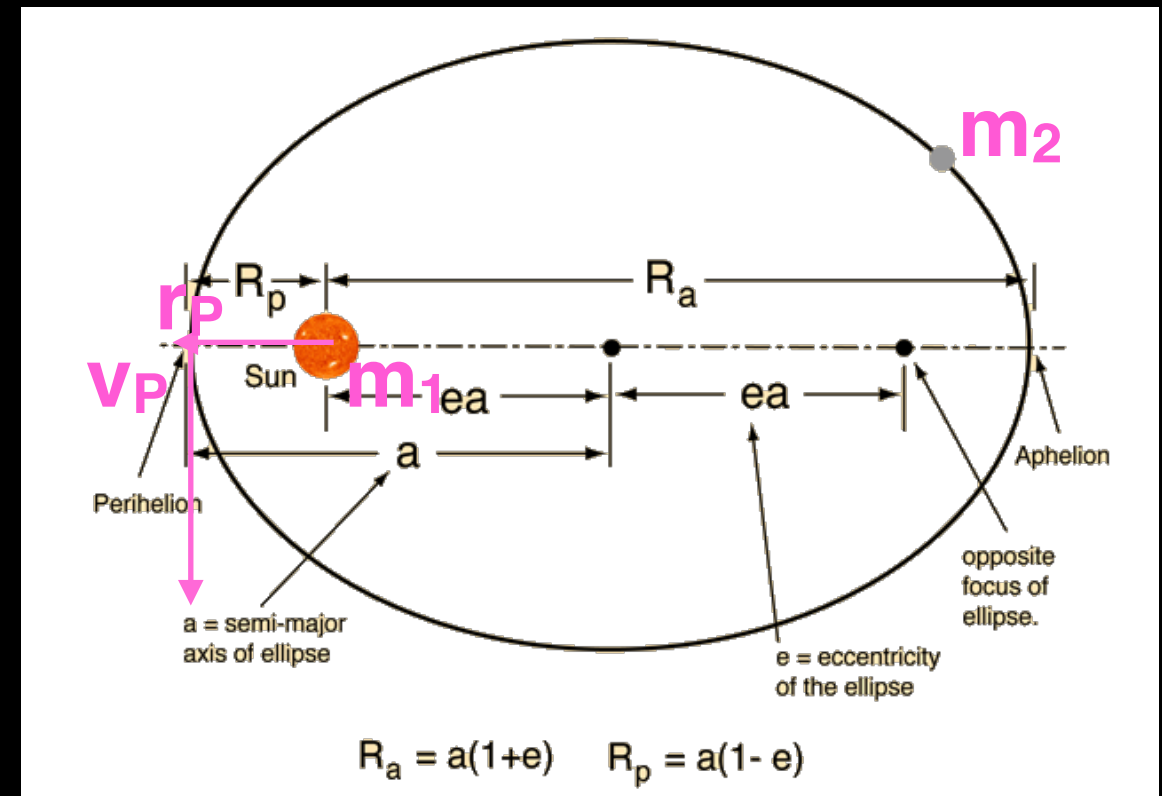
# now, generate the theta array
ntheta = 500 # number of points for theta
th_an = np.linspace(0, 360, ntheta)

# now, create r(theta)
r_an = (a*(1-ecc*ecc))/(1.0 + ecc*np.cos( th_an*np.pi/180.0 ))

# for plotting -> x/y coords for m2
x_an = r_an*np.cos( th_an*np.pi/180.0 )/AUinCM
y_an = r_an*np.sin( th_an*np.pi/180.0 )/AUinCM

# plot x/y coords
fig, ax = plt.subplots(1, figsize = (10, 10))
ax.plot(x_an, y_an, linewidth=5)
plt.show()
```

$$r = \frac{a(1 - e^2)}{1 + e \cos \theta}$$



N-Body Simulations

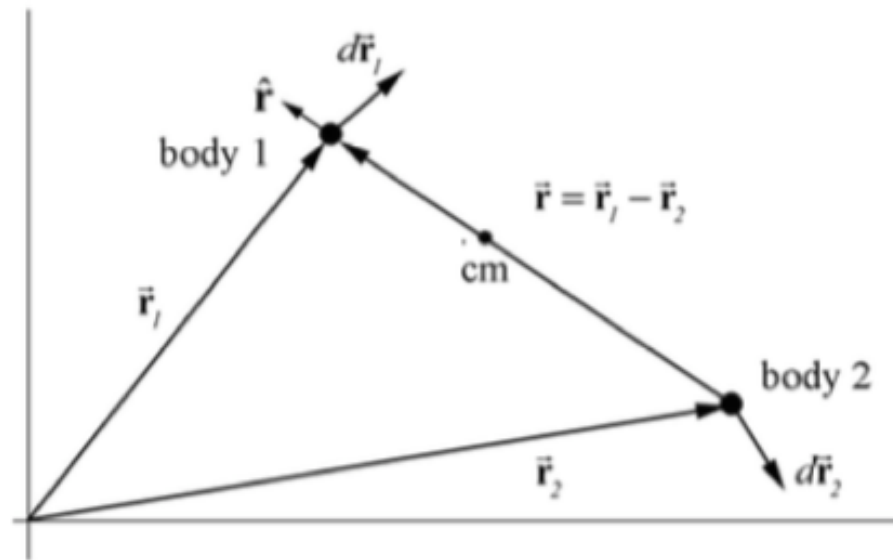
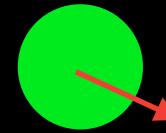


Figure 17.2 Coordinate system for the two-body problem.



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N-Body Simulations

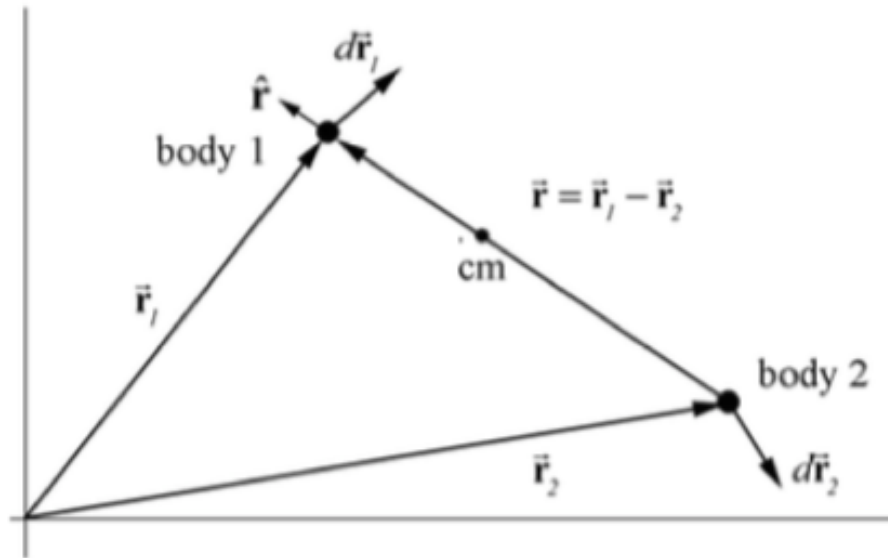
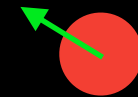
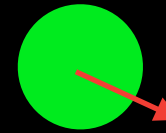


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Ok, but what if we want to solve this problem numerically...

N-Body Simulations

Lets say we look over a small Δt - such that over this small amount of time both the velocity are approximately constant. We know from calculus...

$$a = \frac{dv}{dt}$$

$$dv = a dt$$

$$\int_{v_0}^v dv = \int_0^{\Delta t} a dt$$

$$v - v_0 = a\Delta t$$

$$v = v_0 + a\Delta t$$

$$v = \frac{dx}{dt}$$

$$dx = v dt = (v_0 + at) dt$$

$$\int_{x_0}^x dx = \int_0^{\Delta t} (v_0 + at) dt$$

$$x - x_0 = v_0\Delta t + \frac{1}{2}a\Delta t^2$$

$$x = x_0 + v_0\Delta t + \frac{1}{2}a\Delta t^2$$

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N-Body Simulations

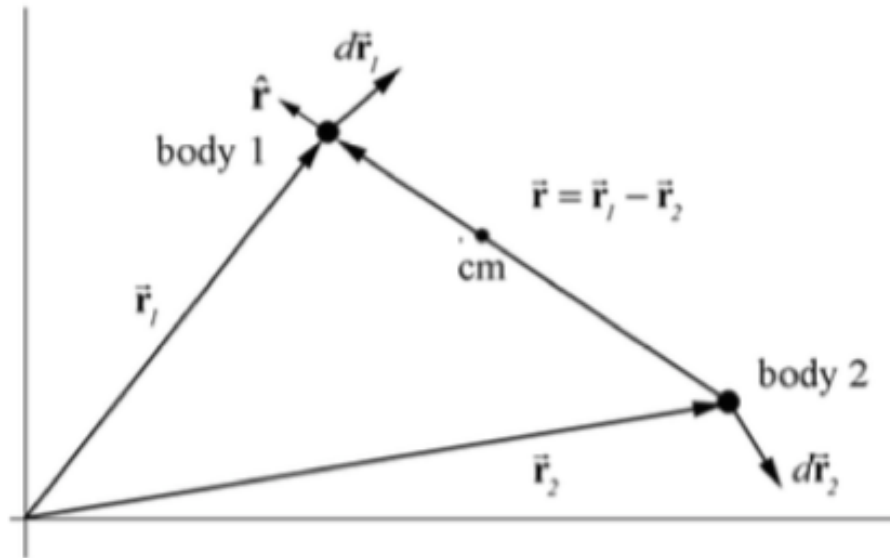


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An itty bitty timestep

$$\Delta t = t_{n+1} - t_n$$

N-Body Simulations

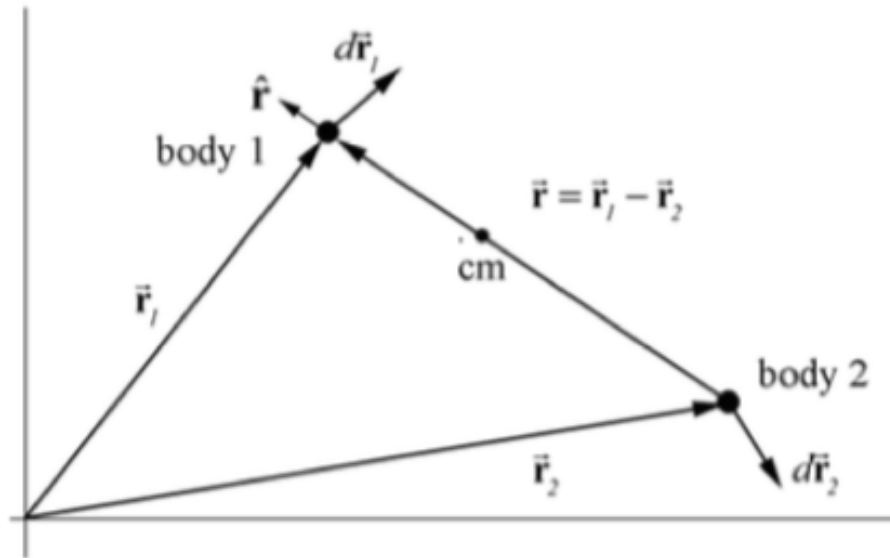


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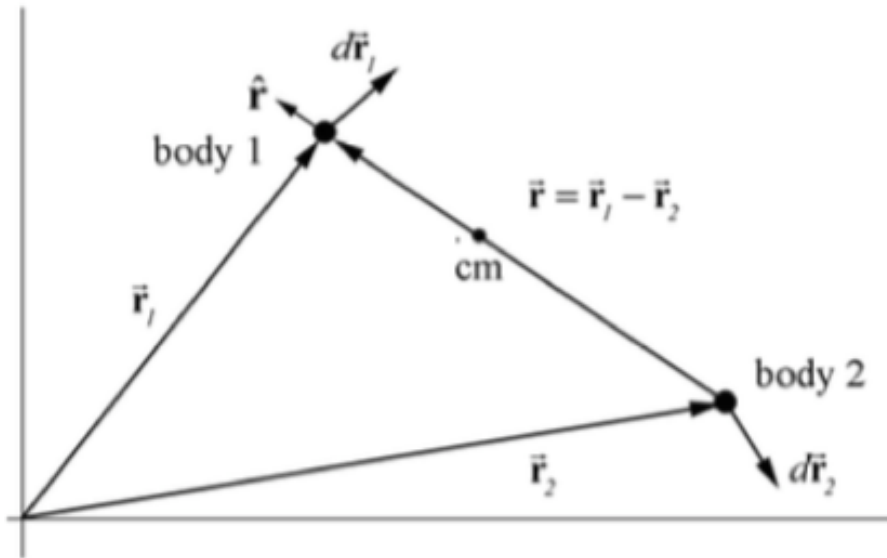


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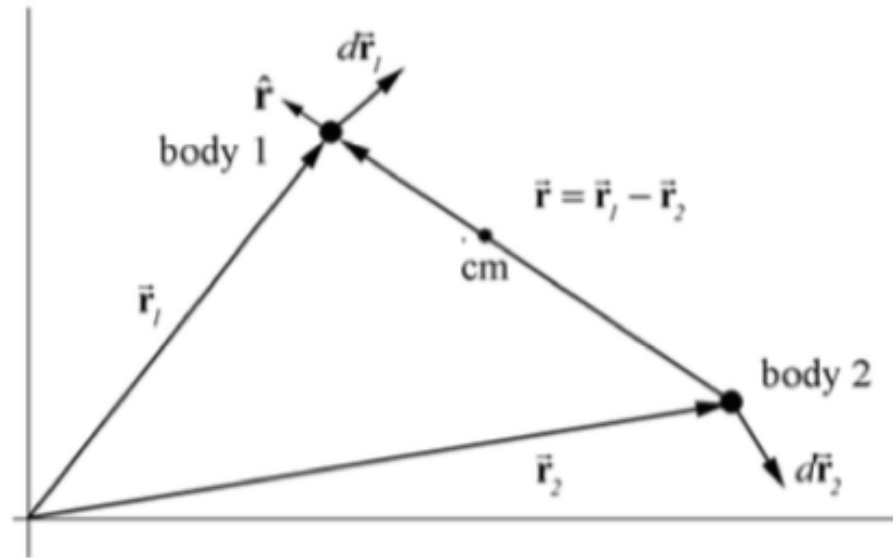


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~ Constant

$$\vec{r}_{1,n+1} = \vec{r}_{1,n} + \vec{v}_{1,n} \Delta t + \frac{1}{2} \vec{a}_{1,n} \Delta t^2$$

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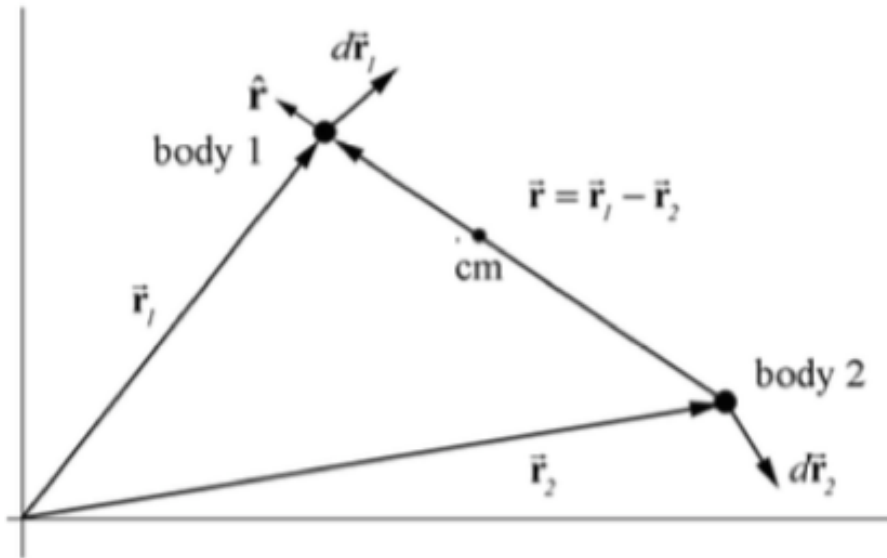


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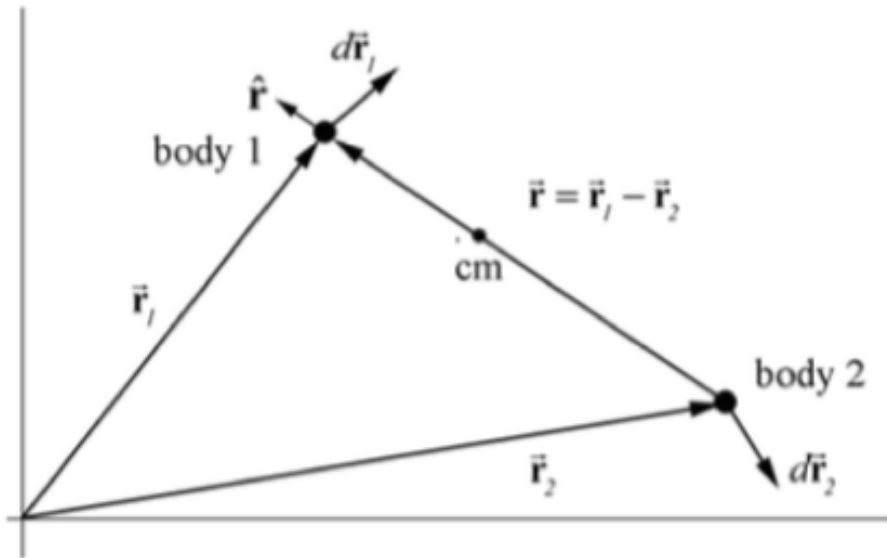


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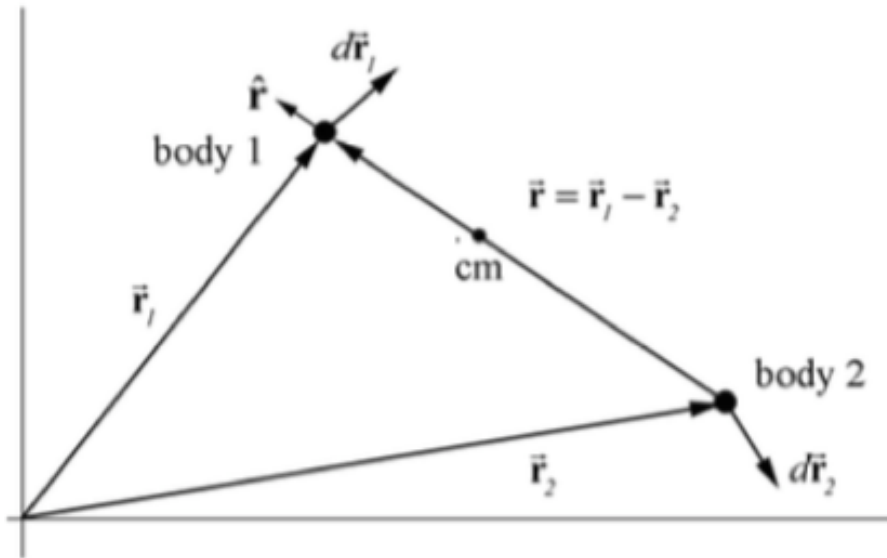


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This simple integration is called a **Euler's Scheme** and gives errors on order of $\sim (\Delta t)^2$ (first order scheme)

** Open up sudo code for Euler's

* A few notes on Inquiry before we get started...

* Download code and go to it!